

Manual

PROFINET

LioN-X IO-Link Master: 0980 XSL 3912-121-007D-00F (8 x IO-Link Class A, Multiprotocol)

LioN-Xlight IO-Link Master: 0980 LSL 3011-121-0006-001 (8 x IO-Link Class A, PROFINET)

0980 LSL 3010-121-0006-001 (4 x IO-Link Class A + 8 x DI, PROFINET)





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1 About this manual

1.1 General information

Please read the assembly and operating instructions in this manual carefully before starting up the modules. Keep the manual where it is accessible to all users.

The texts, figures, diagrams, and examples used in this manual are used exclusively to explain how to operate and apply the modules.

Please contact us if you have any detailed questions on installing and starting up the devices.

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Belden Deutschland GmbH – Lumberg Automation™ – reserves the right to make technical changes or changes to this manual at any time without notice.

1.2 Explanation of symbols

1.2.1 Use of danger information

Danger information is denoted as follows:



Danger: Means that death, serious physical injury or substantial damage to property will occur if the required safety measures are not taken.



Warning: Means that death, serious physical injury or substantial damage to property can occur if the required safety measures are not taken.



Caution: Means that minor physical injury or damage to property can occur if the required safety measures are not taken.

1.2.2 Use of general information

General information is denoted as follows:



Attention: Contains important information on the product, on how to manage the product, or on the respective section of the documentation to which your special attention is being drawn.

1.3 Version information

Index	Created	Changed
Version number	Version 1.0	
Date		

Index	Changed	Changed
Version number		
Date		

Table 1: Overview of manual revisions

2 Safety instructions

2.1 Intended use

The products described in this manual are decentralized IO-Link Masters on an Industrial Ethernet Network.

We adhere to all safety standards when developing, producing, testing, and documenting our products. When you adhere to the handling specifications and safety instructions described for the configuration, assembly, and correct operation, there should not normally be any risks for people or equipment.

The modules fulfill the requirements of the EMC guidelines (89/336/EEC, 93/68/EEC and 93/44/EEC) and the low voltage guideline (73/23/EEC).

The IO-Link Masters are designed to be used in the industrial sector. The industrial environment is distinguished by the fact that the consumer is not connected directly to the public low voltage network. Additional measures are required for use in residential areas or in business and commercial sectors.



Attention: This equipment may cause radio interference in residential areas. In this case the operator may be requested to carry out appropriate measures.

The proper and safe operation of this product depends on proper transportation, storage, assembly, and installation, and careful operation.

A completely assembled device housing is required for the proper operation of the IO-Link Masters. Only connect devices that fulfill the requirements of EN 61558-2-4 and EN 61558-2-6 to the IO-Link Masters.

During the configuration, installation, start-up, maintenance, and testing of the devices, adhere to the safety and accident-prevention guidelines for the specific application.

Only install cables and accessories that fulfill the requirements and regulations for safety, electromagnetic compatibility, and, where applicable, telecommunication end devices, as well as the specification information.

Information on which cables and accessories are permitted for the installation can be obtained from Lumberg Automation $^{\text{TM}}$ or is contained in this manual.

2.2 Qualified personnel

The configuration, installation, start-up, maintenance, and testing of the devices may only be performed by a qualified electrician who is familiar with the safety standards of the automation technology.

The personnel requirements are based on the requirement profiles described by ZVEI, VDMA, or equivalent organizations.

Only electricians who are familiar with the content of this manual are authorized to install and maintain the devices described. These are persons who

- based on their technical training, knowledge, and experience, and their knowledge of the pertinent standards, can evaluate the work to be carried out and identify any potential risks or
- based on working for several years in a related sector, have the same level of knowledge as they would have from the relevant technical training.

Only Belden Deutschland GmbH – Lumberg Automation $^{\text{TM}}$ – is permitted to make changes to the hardware or software of the products that go beyond the scope of this manual.



Warning: Making unqualified changes to the hardware or software, or non-adherence to the warning information contained in this manual, can result in serious personal injury or damage to equipment.



Attention: Belden accepts no liability for any damage caused by unqualified personnel or improper use. This automatically voids the warranty.

3 Designations and synonyms

API	Application Programming Interface	
BF	Bus Fault LED	
Big Endian	Data format with High-B on first place (PROFINET and IO-Link)	
BUI	Back-Up Inconsistency (EIP diagnostics)	
C/Q	I/O port pin 4 mode, IO-Link communication/switching signal	
Ch. A	Channel A (Pin 4) of I/O port	
Ch. B	Channel B (Pin 2) of I/O port	
CIP	Common Industrial Protocol (media independent protocol)	
Class A	IO-Link port specification (Class A)	
Class B	IO-Link port specification (Class B)	
CoAP	Constrained Application Protocol	
DCP	Discovery and Configuration Protocol	
DevCom	Device Comunicating (EIP diagnostics)	
DevErr	Device Error (EIP diagnostics)	
DI	Digital Input	
DIA	Diagnostic LED	
DO	Digital Output	
DIO	Digital Input/Output	
DTO	Device Temperature Overrun (EIP diagnostics)	
DTU	Device Temperature Underrun (EIP diagnostics)	
DUT	Device under test	
EIP	Ethernet/IP	
EIS	EtherNet/IP string	
ERP	Enterprise Resource Planning system	
ETH	ETHERNET	
FE	Functional Earth	
FME	Force Mode Enabled (EIP diagnostics)	

FSU	Fast Start-Up	
GSDML	General Station Description Markup Language	
High-B	High-Byte	
ICE	IO-Link port COM Error (EIP diagnostics)	
ICT	Invalid Cycle Time (EIP diagnostics)	
IDE	IO-Link port Device Error (EIP diagnostics)	
IDN	IO-Link port Device Notification (EIP diagnostics)	
IDW	IO-Link port Device Warning (EIP diagnostics)	
lloT	Industrial Internet of Things	
ILE	Input process data Length Error (EIP diagnostics)	
IME	Internal Module Error (EIP diagnostics)	
I/Q	I/O port pin 2 mode, Digital Input/switching signal	
I/O	Input / Output	
I/O port	X1 - X8	
I/O port pin 2	Channel B of X1 - X8	
I/O port pin 4 (C/Q)	Channel A of X1 - X8	
IOL or IO-L	IO-Link	
ISDU	Indexed Service Data Unit	
IVE	IO-Link port Validation Error (EIP diagnostics)	
I&M	Identification & Maintenance	
JSON	JavaScript Object Notation (platform independent data format)	
L+	I/O port pin 1, sensor power supply	
LioN-X 60	LioN-X variants with a width of 60mm	
Little Endian	Data format with Low-B on first place (EtherNet/IP)	
LLDP	Link Layer Discovery Protocol	
Low-B	Low-Byte	
LSB	Least Significant Bit	
LVA	Low Voltage Actuator Supply (EIP diagnostics)	
LVS	Low Voltage System/Sensor Supply (EIP diagnostics)	
MIB	Management Information Base	

MP	Multi Protocol (PROFINET + EtherNet/IP + EtherCAT® + Modbus TCP)	
MQTT	Message Queuing Telemetry Transport (open networking protocol)	
MSB	Most Significant Bit	
M12	Metric thread according to DIN 13-1 with 12 mm diameter	
OLE	Output process data Length Error (EIP diagnostics)	
OPC UA	Open Platform Communications Unified Architecture (platform independent, service-oriented architecture)	
PLC	Programmable Logic Controller	
PN	PROFINET	
PNS	PROFINET string	
PWR	Power	
REST	REpresentational State Transfer	
RFC	Request for Comments	
RPI	Requested Packet Interval	
SCA	Short Circuit Actuator/U _L /U _{Aux} (EIP diagnostics)	
SCS	Short Circuit Sensor (EIP diagnostics)	
SNMP	Simple Network Management Protocol	
SP	Single Protocol (PROFINET, EtherNet/IP, EtherCAT® or Modbus TCP)	
SPE	Startup Parameterization Error (EIP diagnostics)	
U _{AUX}	U _{Auxiliary}	
UDP	User Datagram Protocol	
U_L	U _{Load} , supply voltage for the load circuit (Actuator supply on Class A IO-Link Master)	
UL	Underwriters Laboratories Inc. (certification company)	
UINT16	Unsigned integer with 16 bits or word in PLC (IW, QW)	
UINT8	Byte in PLC (IB, QB)	

Table 2: Designations and synonyms

4 System description

The LioN modules (Lumberg Automation™ Input/Output Network) function as the interface in an industrial Ethernet system: A central controller on the management level is able to communicate with the decentralized sensors and actuators on the field level. The line or ring topologies for which LioN modules can be used ensure not only reliable data communication but also significantly reduce the number of cables required and thus also the costs for and maintenance. They additionally enable easy and quick extension.

4.1 About LioN-X and LioN-Xlight

LioN-X and the LioN-Xlight variants are IO-Link Masters which convert standard input, standard output or IO-Link signals from sensors & actuators into an industrial Ethernet protocol (PROFINET, EtherNet/IP, EtherCAT®, Modbus TCP) and/or into a cloud protocol (REST API, OPC UA, MQTT). For the first time, there is now Syslog on board. The robust 8 port housing design allows the use even in harsh environments where e.g. weld field immunity, high temperature ranges or protection class IP67 & IP69K are needed. There are also LioN-Xlight single protocol versions available with a limited feature set at a highly attractive price point.

Use all benefits of the Lumberg Automation™ product solution by additionally downloading the configuration tool *LioN-Management Suite V2.0* from www.belden.com to enable e.g. a fast and easy parameterization of the connected IO-Link devices via the embedded IODD interpreter.

4.2 Device variants

The following IO-Link Masters are available in the LioN-X and the LioN-Xlight family:

Article number	Product designation	Description	I/O port functionality
935700001	0980 XSL 3912-121-007D-00F	LioN-X M12-60 mm, IO-Link Master Multiprotocol Security	8 x IO-Link Class A
935701001	0980 LSL 3011-121-0006-001	LioN-Xlight M12-60 mm, IO-Link Master PROFINET	8 x IO-Link Class A
935702001	0980 LSL 3010-121-0006-001	LioN-Xlight M12-60 mm, IO-Link Master PROFINET	4 x IO-Link Class A + 8 x DI
935701002	0980 LSL 3111-121-0006-002	LioN-Xlight M12-60 mm, IO-Link Master EtherNet/IP	8 x IO-Link Class A
935702002	0980 LSL 3110-121-0006-002	LioN-Xlight M12-60 mm, IO-Link Master EtherNet/IP	4 x IO-Link Class A + 8 x DI
935701004	0980 LSL 3311-121-0006-008	LioN-Xlight M12-60 mm, IO-Link Master Modbus TCP	8 x IO-Link Class A
935702004	0980 LSL 3310-121-0006-008	LioN-Xlight M12-60 mm, IO-Link Master Modbus TCP	4 x IO-Link Class A + 8 x DI
935701003	0980 LSL 3211-121-0006-004	LioN-Xlight M12-60 mm, IO-Link Master EtherCAT®	8 x IO-Link Class A

Article number	Product designation	Description	I/O port functionality	
935702003	0980 LSL 3210-121-0006-004	LioN-Xlight M12-60 mm,		
		IO-Link Master	+ 8 x DI	
		EtherCAT®		

Table 3: Overview of LioN-X and LioN-Xlight variants

4.3 I/O port overview

The following tables show the main I/O port differences of the LioN-X IO-Link Master family. Pin 4 and Pin 2 of the I/O ports can be configured partly to IO-Link, Digital Input or Digital Output.

LioN-X

Device variant:	Port	Pin 1 U _S	Pin 4 / Ch. A (C/Q)				Pin 2 /	Ch. B (I/Q)
	Info:	_	Class A	Type 1	Supply by U _S ¹⁾	Supply by U _L ²⁾	Type 1	Supply by U _L ²⁾
	X8:	Out (4 A)	IOL	DI	DO (0.5 A)	DO (2 A)	DI	DO (2 A)
	X7:	Out (4 A)	IOL	DI	DO (0.5 A)	DO (2 A)	DI	DO (2 A)
0980 XSL	X6:	Out (4 A)	IOL	DI	DO (0.5 A)	DO (2 A)	DI	DO (2 A)
3x12	X5:	Out (4 A)	IOL	DI	DO (0.5 A)	DO (2 A)	DI	DO (2 A)
	X4:	Out (4 A)	IOL	DI	DO (0.5 A)	DO (2 A)	DI	DO (2 A)
	X3:	Out (4 A)	IOL	DI	DO (0.5 A)	DO (2 A)	DI	DO (2 A)
	X2:	Out (4 A)	IOL	DI	DO (0.5 A)	DO (2 A)	DI	DO (2 A)
	X1:	Out (4 A)	IOL	DI	DO (0.5 A)	DO (2 A)	DI	DO (2 A)

Table 4: Port configuration of 0980 XSL 3x12... variants

¹⁾ DO switch mode configured as "Push-Pull" (description in the configuration chapters).

²⁾ DO switch mode configured as "High-Side" (description in the configuration chapters).

LioN-Xlight

Device variant:	Port	Pin 1 U _S	Pin 4 / Ch. A (C/Q)			Pin 2 / Ch. B (I/Q)
	Info:	_	Class A	Type 1	Supply by U _S ¹⁾	Type 1
	X8:	Out (2 A)	IOL	DI	DO (0.5 A*)	DI
0980 LSL 3x11	X7:	Out (2 A)	IOL	DI	DO (0.5 A*)	DI
	X6:	Out (2 A)	IOL	DI	DO (0.5 A*)	DI
	X5:	Out (2 A)	IOL	DI	DO (0.5 A*)	DI
	X4:	Out (2 A)	IOL	DI	DO (0.5 A*)	DI
	Х3:	Out (2 A)	IOL	DI	DO (0.5 A*)	DI
	X2:	Out (2 A)	IOL	DI	DO (0.5 A*)	DI
	X1:	Out (2 A)	IOL	DI	DO (0.5 A*)	DI

Table 5: Port configuration of 0980 LSL 3x11... variants

Device variant:	Port	Pin 1 U _S	Pin 4 / Ch. A (C/Q)			Pin 2 / Ch. B (I/Q)
	Info:	-	Class A	Type 1	Supply by U _S ¹⁾	Type 1
	X8:	Out (0.7 A)	-	DI	-	DI
0980 LSL 3x10	X7:	Out (0.7 A)	_	DI	-	DI
	X6:	Out (0.7 A)	-	DI	-	DI
	X5:	Out (0.7 A)	_	DI	_	DI
	X4:	Out (2 A)	IOL	DI	DO (0.5 A*)	DI
	X3:	Out (2 A)	IOL	DI	DO (0.5 A*)	DI
	X2:	Out (2 A)	IOL	DI	DO (0.5 A*)	DI
	X1:	Out (2 A)	IOL	DI	DO (0.5 A*)	DI

Table 6: Port configuration of 0980 LSL 3x10... variants

¹⁾ With DO Switch Mode configured as "Push-Pull" (see description in the configuration chapters).

^{*} For **UL applications**: Max. 0.25 A DO.

5 Overview of product features

5.1 PROFINET product features

Data connection

The connection option provided by LioN-X is the widely-used M12 connector with D-coding for the PROFINET IO network.

The connectors are also color-coded to prevent the ports from being mixed up.

Data transmission rates

Support of 100 Mbit/s with auto crossover and auto negotiation corresponding to IEEE 802.3.

PROFINET RT IO Device

The LioN-X IO-Link Master supports PROFINET RT (real-time). This allows the transmission of time sensitive process data between network components in real-time communication.

PROFINET specification V2.35, Conformance Class C (CC-C)

The LioN-X IO-Link Master complies with the PROFINET specification V2.35 and meet the requirements of Conformance Class C (CC-C) for the integrated switch. This means the device can be used in PROFINET IRT networks.

Integrated switch

The integrated Ethernet switch with Conformance Class C (CC-C) has two PROFINET ports and thus supports the establishment of a line or ring topology for the PROFINET IO network.

Media Redundancy Protocol

The additionally implemented Media Redundancy Protocol (MRP) enables the design of a highly available network infrastructure.

Fast Start-Up (FSU)

Fast Start-Up is an accelerated start-up process that enables LioN-X Masters to start communicating on a PROFINET network after a very short time. This makes a faster tool change possible, for example. Thanks to the FSU feature, the network is ready to communicate in less than 2200 ms.¹

Shared Device

With the shared device functionality, two controllers can access the same I/O device via a PROFINET interface. This option is done by copying the configuration of the I/O device into the first and second controller and assigning it to the second controller as shared device. Every sub slot with I/O data can be assigned to **one** of the two PLCs which share the I/O data of the I/O device.

DCP

The Masters use the DCP protocol to automatically assign IP addresses.

Net Load Class III

The devices offer advanced robustness against net load according to Net Load Class III .

LLDP

The LLDP protocol is used to detect devices in the vicinity (neighborhood detection).

SNMPv1

Measured according to the specification: Internal switch is able to forward telegrams.

The SNMPv1 protocol (according PROFINET standard V2.35) handles network component monitoring and communication between Master and Device (cannot be operated stand-alone).

Alarm and diagnostic messages

The modules support extended PROFINET alarm and diagnostic messages.

I&M functions

Identification and maintenance data (I&M) means information stored on the module. The identification data consist of manufacturer details for the module and can only be read. The maintenance data consist of system specific details created during the course of configuration. The modules can be uniquely identified online via the I&M data.

The device supports I&M data related to the PNO 2.832 standard (IO-Link integration for PROFINET, Edition 2): I&M0 ... I&M3 for the interface module (access slot, sub-slot 0x8000)

I&M0 for the IO-Link Master proxy I&M0 and I&M5 for the IO-Link Device proxies

GSDML-based configuration and parameterization of the I/O ports

The GSDML offers the option of configuring and parameterizing the I/O ports on the master devices within an engineering tool of a PLC.

5.2 I/O port features

IO-Link specification.

LioN-X is ready for IO-Link specification v1.1.3.

8 x IO-Link Master ports

Depending on the variant, the IO-Link Master has 4 IO-Link Class A or 8 IO-Link Class A ports with an additional hard-wired digital input on pin 2 of the I/O port. For detailed information see chapter I/O port overview on page 19.



Warning: If devices with electric isolation and devices without electric isolation are used within the same system, the electric isolation of all connected devices is annulled.

IO-Link port connections

The IO-Link port connection option provided by LioN-X devices is the 5-pin M12 connector. Pin 5 is not assigned for IO-Link Class A ports.

Validation & Backup

The Validation & Backup function checks if the right device is connected and stores the parameters of the IO-Link Device. The function thus gives you an easy option for replacing the IO-Link Device.

This is possible as of IO-Link specification V1.1 and only if the IO-Link Device **and** the IO-Link Master support the function.

IO-Link Device parameterization

IO-Link Device parameterization in a PROFINET network is possible via the Siemens IO_LINK_DEVICE function block (FB50001) for Siemens TIA Portal[®].

LED

You can see the status of a port by the color of the matching LEDs and their flash pattern. For details on the

meanings of the LED colors, please see section LEDs on page 199.

5.3 Integrated Web server

Network parameter display

Get an overview of network parameters such as the IP address, subnet mask and gateway.

Displaying diagnostics

View diagnostics via the integrated Web server.

User management

Use the integrated Web server for convenient management of all users.

IO-Link Device parameters

You can read the IO-Link Device parameters and write new parameters in single write mode (single write mode doesn't activate the automated mechanism of the "Validation and Backup" function) to the IO-Link Device.

5.4 Security features

Firmware signature

All official firmware update packages contain a signature which prevents the system against manipulated firmware updates.

Syslog

The LioN-X multiprotocol variants support the traceability of messages centrally managed and logged via Syslog.

User manager

The Web server provides a user manager to protect the Web interface against unauthorized access. You can manage the allowed users by different access levels "Admin" or "Write".

Default user settings:

User: admin

Password: private



Attention: Change the default settings to protect the device against unauthorized access.

5.5 Other features

Interface protection

The modules have reverse polarity, short-circuit and overload protection for all interfaces.

For more details, see section Port assignments on page 33.

Failsafe

The modules support a failsafe function. This allows you to define the behavior of every single channel configured as an output in the case of a loss of the PLC communication.

Industrial Internet of Things

LioN-X is industry 4.0 ready and supports the integration in IIoT networks via REST API and the IIoT-relevant protocols MQTT, OPC UA and CoAP.

Color-coded connectors

The green-colored connectors help you avoid confusion in your cabling.

IP protection classes: IP65 / IP67 / IP69k

The IP protection class describes environmental influences that the devices can be exposed to without risk and without suffering damage, or causing a risk for the user

The whole LioN-X family offers IP65, IP67 and IP69k.

6 Assembly and wiring

6.1 General information

Mount the device on a flat surface using 2 screws (M4x 25/30). The torque required here is 1 Nm. Use washers for all fastening methods as per DIN 125.



Attention: The devices have a ground connection with an M4 thread for the conduction of interference currents and the EMC immunity. This is labeled with the symbol for the ground and the designation "FE"



Attention: Use a low-impedance connection to connect the device to the reference ground. When using a grounded mounting surface, you can make the connection directly via the fixing screws.



Attention: If the mounting surface is ground-free, use a ground strap or a suitable FE line (FE = Functional Earth). Use an M4 screw to connect the ground strap or the FE line to the ground point and if possible put a washer and a toothed washer below the fixing screw.

6.2 Outer dimensions

6.2.1 LioN-X multiprotocol variants

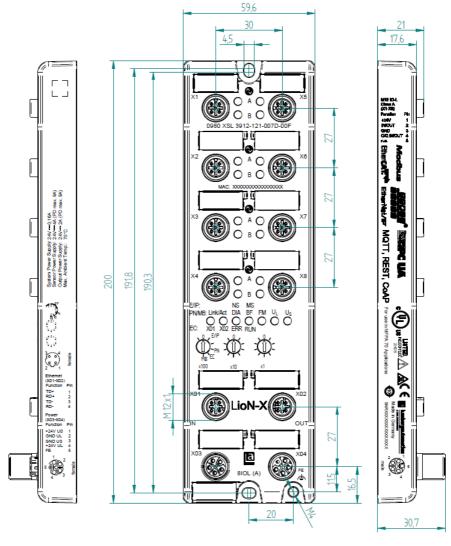


Figure 1: 0980 XSL 3912-121-007D-00F

6.2.2 LioN-Xlight variants with PROFINET

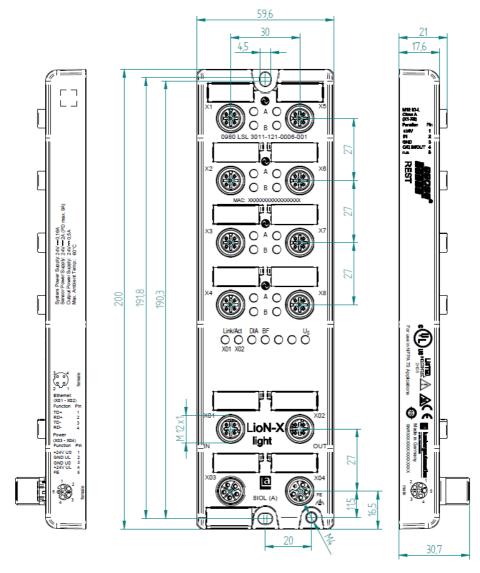


Figure 2: 0980 LSL 3011-121-0006-001

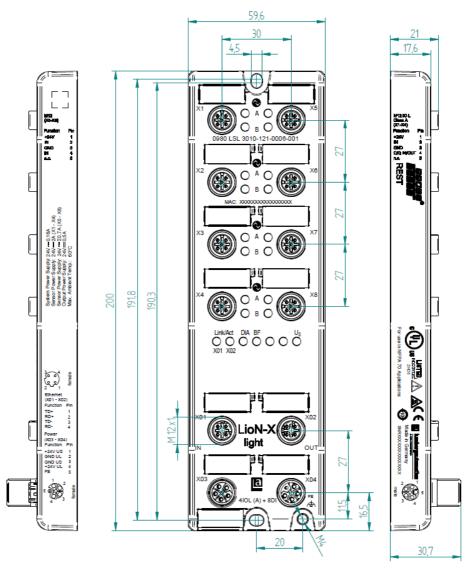


Figure 3: 0980 LSL 3010-121-0006-001

6.2.3 Notifications



Attention:

For **UL applications**, be sure to use a UL-certified cable with a suitable evaluation to connect the devices (CYJV or PVVA). To program the control, please refer to the OEM information, and only use suitable accessories.

Only approved for interior use. Please note the maximum elevation of 2000 meters. Approved up to a maximum soiling level of 2.



Warning: Terminals, housings field-wired terminal boxes or components can exceed temperatures of +60 °C (140 °F).



Warning: For **UL applications** at a maximum ambient temperature of +70 °C (158 °F):

Use temperature-resistant cables with heat resistance up to at least +115 °C (239 °F) for all LioN-X and LioN-Xlight variants.



Warning: Observe the following maximum output power for the sensor supply:

Max. 2.0 A per channel; max. 6.5 A in total (for **UL applications** max. 5 A in total) for every port pair (X1/X2, X3/X4, X5/X6, X7/X8); max. 9.0 A in total (with derating) for the whole port group (X1 .. X8).

6.3 Port assignments

All the contact arrangements shown in this chapter show the frontal view of the connection area for the connectors.

6.3.1 Ethernet ports, M12 socket, 4-pin, D-coded

Color coding: green



Figure 4: Schematic drawing, ports X01, X02

Port	Pin	Signal	Function
Ethernet	1	TD+	Transmit data plus
Ports X01, X02	2	RD+	Receive data plus
	3	TD-	Transmit data minus
	4	RD-	Receive data minus

Table 7: Assignment of ports X01, X02



Caution: Risk of destruction! Never connect the power supply to the data cables.

6.3.2 Power supply with M12 power L-coded

Color coding: gray



Figure 5: Schematic diagram of the M12 L-coding (connector X03 for Power In)



Figure 6: Schematic diagram of the M12 L-coding (socket X04 for Power Out)

Power supply	Pin	Signal	Function
	1	U _S (+24 V)	Sensor/system power supply
	2	GND_U _L	Ground/reference potential U _L
3 GNE		GND_U _S	Ground/reference potential U _S ¹
	4	U _L (+24 V)	Load supply (NOT electrically isolated to U _S internally in device)
	5	FE (PE)	Functional ground

Table 8: Power supply with M12-Power



Attention: Only use power supply units for the system/sensor and actuator supply that correspond to PELV (Protective Extra Low Voltage) or SELV (Safety Extra Low Voltage). Power supplies

² U_I and U_S ground connected in device

according to EN 61558-2-6 (transformers) or EN 60950-1 (switching power supply units) fulfill these requirements.

6.3.3 I/O ports as M12 sockets

6.3.3.1 IO-Link Class A

Color coding: black



Figure 7: Schematic drawing I/O port as M12 socket IO-Link Class A

		·	
0980 XSL 3x12-121	Pin	Signal	Function
IO-Link Class A, ports X1 - X8	1	+24 V	power supply +24 V
X1 - X8	2	IN/OUT	Ch. B: Digital inputs or digital outputs
	3	GND	Ground/reference potential
	4	C/Q IN/OUT	Ch. A: IO-Link data communication, digital input or digital output
	5	n.c.	not connected
0980 LSL 3x11-121	Pin	Signal	Function
IO-Link Class A, ports	1	+24 V	power supply +24 V
X1 - X8	2	IN	Ch. B: Digital inputs
	3	GND	Ground/reference potential
	4	C/Q IN/OUT	Ch. A: IO-Link data communication, digital input or digital output
	5	n.c.	not connected
0980 LSL 3x10-121	Pin	Signal	Function
IO-Link Class A, ports	1	+24 V	power supply +24 V
X1 - X4	2	IN	Ch. B: Digital inputs
	3	GND	Ground/reference potential
	4	C/Q IN/OUT	Ch. A: IO-Link data communication, digital input or digital output
	5	n.c.	not connected
IO-Link Class A, ports X5 - X8	1	+24 V	power supply +24 V
ΛΌ - ΛΌ	2	IN	Ch. B: Digital inputs

Table 9: I/O ports as M12 socket IO-Link Class A

GND

C/Q IN

n.c.

3

4

Ground/reference potential

digital input

not connected

Ch. A: IO-Link data communication,

7 Starting operation

7.1 GSDML file

A GSD file in XML format is required to configure the LioN-X and LioN-Xlight variants. All device variants are grouped in a single GSDML file. The file can be downloaded from the product pages on our online catalog: catalog.belden.com

On request, the GSDML file is also sent by the support team.

The GSDML file and the associated bitmap files are grouped in the archive file named GSDML-V2.35-BeldenDeutschland-LioN-X-yyyymmdd.xml.

yyymmdd stands for the date on which the file was issued.

Download this file and unpack it.

In Siemens TIA Portal[®] you create a new project and open the hardware manager under **Configure a device**. Under the menu command **Options** > **Manage general station description files (GSD)** the GSD file is installed by defining the file path.

The LioN-X and LioN-Xlight variants are then available in the hardware catalog.

7.2 MAC addresses

Every device has three unique assigned MAC addresses that cannot be changed by the user. The first assigned MAC address is printed onto the device.

7.3 State on delivery

PROFINET parameters in state on delivery or after a factory reset:

PROFINET name:	Name not assigned
IP address:	0.0.0.0
Subnet mask:	0.0.0.0
Device designations:	0980 XSL 3912-121-007D-00F 0980 LSL 3011-121-0006-001 0980 LSL 3010-121-0006-001
Vendor ID:	0x016a
Device ID:	0x0400

7.4 Setting the rotary encoding switches



Attention: Only applicable for LioN-X multiprotocol variants; not applicable for LioN-Xlight variants.

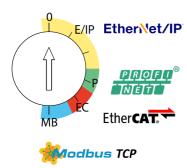
The LioN-X multiprotocol variants allow you to select different protocols for communication within an industrial Ethernet system. In this way the IO-Link Masters with multiprotocol function can be integrated into different networks without it being necessary to purchase products specific for each protocol. This technology also gives you the option to use the same IOL-Master in different environments.

Using rotary encoding switches at the lower front of the devices, you can easily and conveniently set both the protocol and the address of the device, if the protocol to be used supports this. Once you have made a protocol selection and started the cyclical communication, the device stores this setting permanently and uses the selected protocol from this point on. To use another supported protocol with this device, perform a factory reset.

The following LioN-X IO-Link Master variants support multiprotocol application for the protocols EtherNet/IP (E/IP), PROFINET (P), EtherCAT® (EC) and Modbus TCP (MB):

▶ 0980 XSL 3912-121-007D-00F

The multiprotocol devices have a total of three rotary encoding switches. With the first rotary encoding switch (x100) you set the protocol by using the corresponding switch position. Additionally, x100 is used to set the third last digit of the IP address for EIP.



With the other rotary encoding switches (x10 / x1), you set the last two digits of the IP address when you are using EtherNet/IP or Modbus TCP.

Protocol	x100	x10	x1
EtherNet/IP	0-2	0-9	0-9
PROFINET	Р	-	-
EtherCAT®	EC	-	-
Modbus TCP	МВ	0-9	0-9

Table 10: Assignment of the rotary encoding switches for each protocol

The setting you make to select a protocol is described detailed in the protocolspecific sections.

In delivery state no protocol settings are stored in the device. In this case only the desired protocol has to be chosen. To take over a changed rotary encoding switch setting (protocol setting), a power cycle or "Reset" from the Web interface is necessary.

Once you have set the protocol using the rotary encoding switches, the device stores this setting when it starts in cyclic communication. Changing the protocol using the rotary encoding switch is no longer possible after this point. The device will always start using the stored protocol from that point on. The IP address can be changed depending on the selected protocol.

To change the protocol, carry out a factory reset. In this way you restore the factory settings of the respective device. How you perform the factory reset for your device is described in chapter Factory reset on page 41.

If you position the rotary encoding switch in a manner that is invalid, the device signals this to you with a blink code (the BF/MS LED blinks in red three times).

7.4.1 PROFINET

If you decide to use PROFINET, set the first rotary encoding switch to the value of P.

7.4.2 Factory reset

A factory reset restores the original factory settings and thus resets the changes and settings you have made up to that point. It also resets the protocol selection. To perform a factory reset, set the first rotary encoding switch (x100) to 9, the second (x10) to 7, and the third (x1) also to 9.

Afterwards perform a power cycle and wait 10 seconds due to internal memory write processes.

During the factory reset, the U_S LED is blinking red. After the internal memory write processes have finished, the U_S LED returns to display static green or red light, in dependency of the actual U_S voltage.

	x100	x10	x1
Factory Reset	9	7	9

Follow the steps from section Setting the rotary encoding switches on page 39 again to select a new protocol.

For performing a factory reset via software configuration, see chapter OPC UA configuration on page 149 and the configuration section.

7.5 SNMPv1

The PROFINET IO-Link Master supports SNMP objects required by the PROFINET specification as per protocol standard SNMPv1. These include objects from RFC 1213 MIB-II (System Group and Interfaces Group) and the LLDP MIB.

Passwords:

Read Community: publicWrite Community: private

8 Configuration and operation with SIEMENS TIA Portal®



Attention: The displayed examples of SIEMENS TIA Portal[®] have been made with TIA V15.

After installing the GSDML files for the LioN-X PROFINET variants, they are available in the hardware catalog under **Other field devices** > **PROFINET IO** > **IO** > **Belden Deutschland GmbH - Lumberg Automation** > **Lumberg Automation LioN-X**.

- First, configure the TIA Portal[®] project and the control system in the usual way. Assign an IP address and subnet mask for the PROFINET port of the control unit.
- 2. Then choose the desired device from the Hardware catalog:

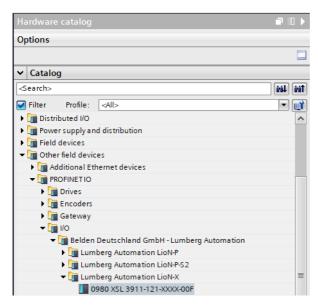


Figure 8: TIA Portal® Hardware catalog

3. Click on the article designations of the modules in the hardware catalog and drag and drop the desired device into the network view:

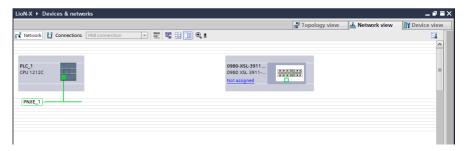


Figure 9: Network view

4. Assign the device to the PROFINET network:

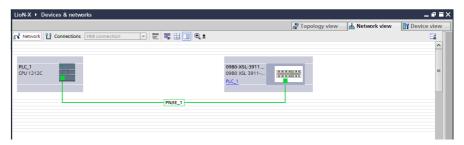


Figure 10: Assign device

5. Switch to the device configuration view and select the device to display configuration options:

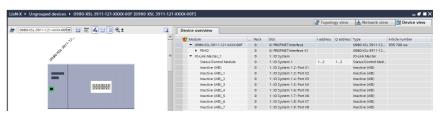


Figure 11: Device configuration

8.1 Assigning a device name and IP address

PROFINET IO devices are addressed on PROFINET via a unique device name. This can be freely assigned by the user, but may only be used once on the network.

1. A click on the device icon or on the first line of the **Device overview** opens the settings for **PROFINET interface** > **Ethernet addresses**:



Figure 12: ETHERNET addresses

- Check that the control unit and the IO device are on the same Ethernet Subnet.
- Accept the default settings for IP address and device name or change them if desired.
- **4.** For a correctly working setup, the chosen device name must be programmed online in the IO device. When the HW is already installed, you can easily change to online mode. The new IO device should already be accessible via PROFINET:



Figure 13: Go online

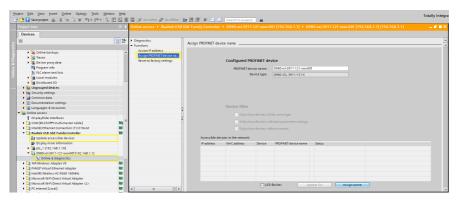


Figure 14: Online mode

5. Enter the same device name as configured in the offline project:



Figure 15: Assign device name

8.2 Configuring the IO-Link channels

By default, all channels are pre-configured as digital input.

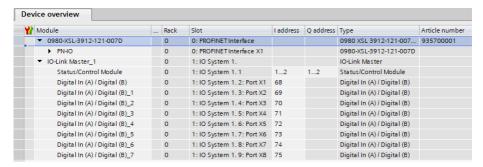


Figure 16: Channels pre-configuration

The configurations of the IO-Link channels (C/Q or Ch. A/Pin 4 of the I/O port) in the sub-slots 2 - 9 (port X1 of the device is equivalent to sub-slot 2, ..., port X8 of the device is equivalent to sub-slot 9) are flexibly definable.

The input and output addresses defined in the device overview can be changed.

8.2.1 Deleting the configuration of a specified IO-Link channel

1. To delete an IO-Link channel, select the desired IO-Link channel(s) in Device overview:

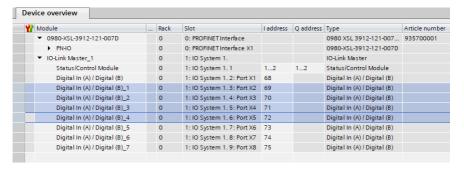


Figure 17: Device overview

2. Right click and then select the **Delete** option in the menu that appears:

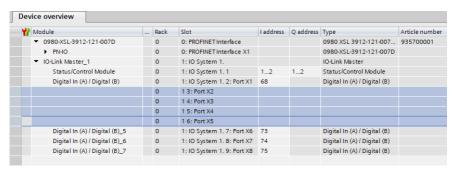


Figure 18: Free IO-Link channel(s)

8.2.2 Creating an IO-Link channel configuration

The **Submodules** folder of the I/O device inside the **Hardware catalog** shows all configurable options that can be selected:

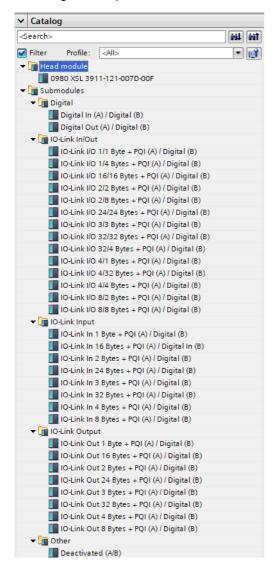
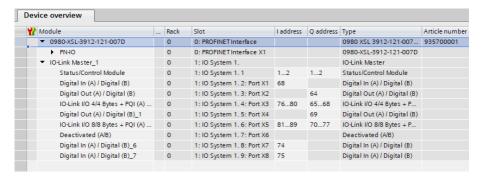


Figure 19: IO-Link channel configuration

Select the desired option, click and hold down the left mouse button to drag the configuration to a free IO-Link sub-slot:



The following options are available for the IO-Link C/Q channel (Ch. A/Pin 4):

Digital In (DI)

In this mode the channel operates as a digital input.

Digital Out (DO)

In this mode, the channel operates as a digital output.

Deactivated

This mode should be selected if the A-channels and the B-channels of the I/O ports (ports X1-X8) are not used. The L+ power supply (pin 1) of the port is disabled in this case.

IO-Link ...

In this mode (IO-Link communication mode), the process data from or to the device are exchanged over a communication link. Depending on the port configuration, the IO-Link Master automatically starts communicating with the connected IO-Link Device, taking into account the baud rate. Additionally, this mode offers the option of parameterizing the IO-Link Device. Configuration modules with data lengths of 1-33 bytes for physical inputs and 1-32 bytes for physical outputs are available. If no suitable configuration module is available for the device, the

next larger data length must be selected. After the first configuration of the device, this port configuration will be stored non-volatile on the IO-Link Master. This means that with the next power-up the I/O port will be pre-configured with these settings before the controller will send a new port configuration. The sensor supply (I/O port Pin 1) and the auxiliary supply (I/O port Pin 2) will be powered up directly depending on the last active configuration. A configuration telegram of the PN-Controller is not being required. The I/O data remain invalid until a new configuration is received after the power-up of the IO-Link Master.

8.3 Parameterization of the Status/Control Module

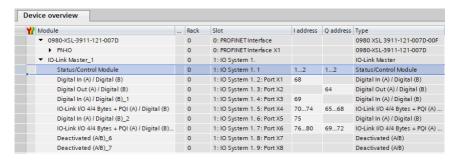


Figure 20: Status/Control Module

Parameters within the Status/Control Module:



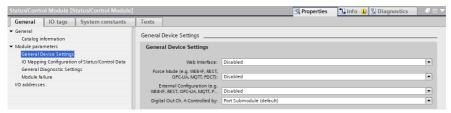
Figure 21: Parameters Status/Control Module

The Status/Control Module in slot 1/sub-slot 1 is pre-configured for each LioN-X IOL-Master. It consists of 2 bytes of input and 2 bytes of output data for the digital I/O data. The bit assignments are described in Section Process data assignment on page 111.

The Status/Control Module can also be used to perform some general parameterizations that do not affect any functionality of channels in IO-Link mode.

The following parameterizations are possible after clicking on the subitems under the **Module parameters**:

8.3.1 General Device Settings



Web Interface

The Web interface access can be set to "Enabled" or "Disabled" with this parameter. In case of the "Disabled" setting, the Web pages are not reachable.

Default: Enabled

Force Mode

The input and output I/O data can be forced (= changed) for implementation reasons. This can be done by different interfaces (e.g. Web-Interface, REST, OPC-UA, MQTT). The support of interfaces for Forcing depends on the chosen software variant. With this function the possibility of forcing I/O data can be enabled or disabled.

Default: Disabled



Danger: Risk of physical injury or death! Unattended forcing can lead to unexpected signals and uncontrolled machine movements.

External Configuration

Configuration and parameter data can be set over different external interfaces outside the GSDML configuration (e.g. Web-Interface, REST, OPC-UA, MQTT). With this option, the "External Configuration" can be enabled or disabled. An external configuration is only valid until a new configuration is received by the PROFINET controller.

Default: Disabled

Digital Out Ch. A controlled by...

Port Sub-module:

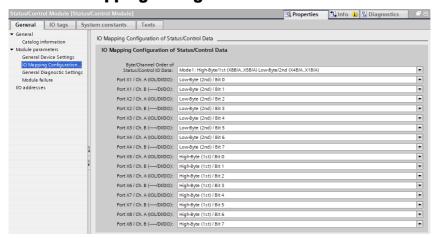
For controlling the digital A-channels, the output **Byte 1**/**Bit 0** of the appropriate sub-slot module must be used.

Status/Control Module:

In this case, the digital A-channel outputs can be controlled by the Status/Control Module output bits. The digital output can be controlled only by one data source.

Default: Port Sub-module

8.3.2 I/O mapping configuration of Status/Control data



Byte/Channel order of Status/Control I/O data

With this parameter, 4 (Mode 1-4) pre-defined bit mappings for the digital I/O bits can be selected. The I/O data will be mapped to the Status/Control Module's input and output bytes.

Mode 5 can be used for a free, user defined mapping. The parameter settings "Port X1 / Channel A" — "Port X8 / Channel B" must be used for this. These parameters enable all I/O channels to be freely assigned to a Bit in the Status/ Control I/O data. It should be noticed that duplicate assignments are not possible here. If faulty parameterization is detected in the LioN-X module, a fault will be registered.

When chosen Mode 1 – Mode 4, the "Port X1 / Channel A" – "Port X8 Channel B" settings will be ignored in the LioN-X module.

The chosen mapping will be used in the same way for input and output data direction.

Mode 1:



Mode 2:



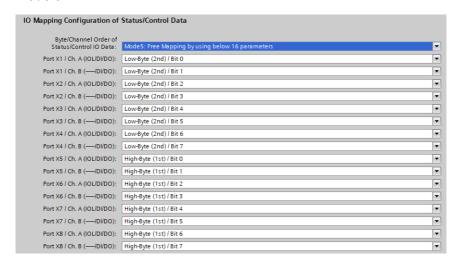
Mode 3:



Mode 4:

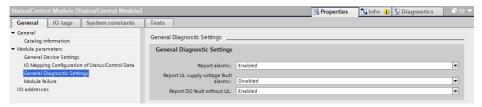


Mode 5:



For detailed I/O mapping refer to chapter Process data Status/Control Module, I/O system 1.1 on page 111.

8.3.3 General Diagnostic Settings



Report alarms

With this parameter, all diagnosis messages can be enabled or disabled.

Default: Enabled

Report U₁ supply voltage fault alarms

The U_L supply voltage fault alarm can be set to "Disabled", "Enabled" or "Auto Mode" with this parameter.

In "Auto Mode", the U_L diagnosis will be activated with the first rising slope detection after power-up.

Default: Disabled



Attention: "Report U_L supply voltage fault" is disabled in the default setting to avoid diagnostic messages due to switching the supply voltage on or off later on.

Report DO fault without UL

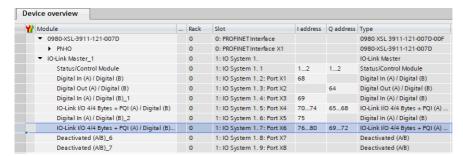
The diagnosis of digital outputs can be configured in dependency of the U_L status.

When the output will be active without active U_L while this parameter is set to "Enabled", a diagnosis message will be generated for the output channel.

Default: Enabled

8.4 Parameterization of the I/O ports X1 – X8

In the device configuration mode, click on the corresponding IO-Link sub-slot in the Device overview and select the Module parameters for setting the following parameters:



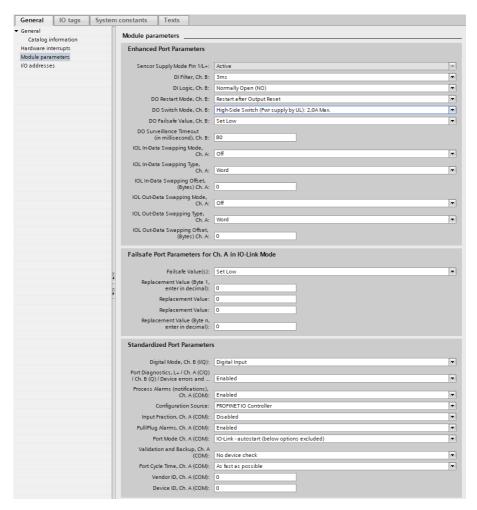


Figure 22: Parameter of the IO-Link channels

8.4.1 Enhanced port parameters

In dependency of the configured sub-module, some of the following described parameters can differ. (available only for special channel, otherwise not available)

Sensor Supply Mode Pin 1 / L+

The sensor supply on pin 1 is always active and cannot be disabled.

DI Filter

With this parameter, the filter time of the digital input can be defined. The following options are available:

Off: 1 ms: 2 ms: 3 ms: 6 ms: 10 ms: 15 ms

Default: 3 ms

DI Logic

This parameter can be used to configure the logic of the channels used as digital inputs.

NO (Normally Open)

A non-damped sensor has an open switching output (low signal) in this case. The device input detects a low signal and returns a 0 to the control unit.

The LED of the channel shows the physical input state.

NC (Normally Closed)

A non-damped sensor has a closed switching output (high signal) in this case. The device input detects a high signal, inverts the signal, and returns a 0 to the control unit.

The channel LED displays, independent of the setting, the physical input state.

Default: NO (Normally Open) for all channels

DO Restart Mode

With this parameter, the digital output restart behavior can be set.

Automatic Restart after Failure:

In case of detecting an output short circuit or overload, the output will be switched off by the IO-Link Master. However, after a time delay, the output will automatically be turned on again for checking if the overload or short circuit condition is active.

Restart after Output Reset:

In case of detecting an output short circuit or overload, the output will be switched off by the IO-Link Master.

The output will not be set automatically. Before the output can be turned on again, it must be logically reset by the PLC.

Default: Automatic Restart after Failure

DO Switch Mode (only 0980 XSL... variants)

With this option, the mode of the digital output switch can be selected.

Push Pull Switch (0.5 A):

In this mode, the output will be switched active to high and low. In low state, the output can be a current sink. In this mode, the digital output will be supplied by $U_{\rm S}$.

High-Side Switch (0.5 A; 1.0 A; 1.5 A; 2.0 A; 2.0 A Max.): In this mode, the output will be switched active to high, but not to low. Output low means high impedance at digital output. Additionally, the current limitation can be selected for each digital output in High-Side Switch mode. This means that the level for actuator overload diagnostic can be managed by this selection. 2.0 A Max. means, that current limitation is **not** active and the maximum output current for this output is available. In these modes, the digital output will be supplied by U_L or U_{Aux} , depending on the device variant.

Refer to chapter I/O port overview on page 19 for the voltage supply of the digital outputs.

Default: High-Side Switch (2.0 A Max.)

DO Failsafe Value

The device supports a failsafe function for the channels used as digital outputs. During configuration of the devices, the status of the PROFINET IO device outputs can be defined after an interruption, or loss of communication on the PROFINET IO network.

The following options can be selected:

Set Low - the output channel is disabled and/or the output bit set to 0.

Set High - the output channel is enabled and/or the output bit set to 1.

Hold last – the last output state is kept.

Default: Set Low

DO Surveillance Timeout

For channels configured as digital output, the firmware of the modules allows you, for this special use case, to set a delay time before output status monitoring is enabled.

The delay time is referred to as the "Surveillance-Timeout" and can be configured for each output channel. The delay time begins with a rising edge of the output control bit. After this time has elapsed, the output is monitored, and error states are reported by diagnostics.

The "Surveillance-Timeout" parameter can be set from 0 to 255 ms. When an output channel is in static state. i.e., when the channel is permanently switched on or off, the typical filter value (not changeable) before a diagnostic message is 5 ms.

Default: 80 ms

IO-Link Input/Output Data Swapping

With the following parameters, the IO-Link byte data order can be setup separately for Input and Output data direction.

Swapping Mode

The byte order swapping will be made for the selected count of data types or for the complete length of IO-Data with the selected Data Type (Word = 2 Bytes or DWord = 4 Bytes).

Default: Off

Swapping Data Type

The swapping can be setup to Word (2 Bytes) or DWord (4 Bytes)

- → Word Swapping: Byte 1 Byte 2 => Byte 2 Byte 1
- \rightarrow DWord Swapping: Byte 1 Byte 4 => Byte 4 Byte 1

The Data Type value has no effect when the Swapping Mode is setup to "Off".

Default: Word

Swapping Offset

A swapping offset in bytes can be setup in dependency of the configured IO-Data length.

When setup to "2", the swapping will be processed from the 3rd Byte.

Default: 0

8.4.2 Failsafe port parameters for Ch. A in IO-Link mode

The following values are selectable (for output data only):



Figure 23: Failsafe Configuration

For a proper function of the IO-Link failsafe values, the IO-Link Device parameters should be set in the same way, if possible. In the case of a lost network connection, the IO-Link Master sends, according to its failsafe configuration, output data to the IO-Link Device. If the IO-Link Device connection is lost, the IO-Link Device uses the failsafe options parameterized inside the device, if supported.

When the device supports a failsafe mechanism, choose the option IO-Link Master Command.

Set Low

All bits of the output data with a value of 0 are transmitted to the IO-Link Device. (Default setting)

Set High

All bits of the output data with a value of 1 are transmitted to the IO-Link Device.

Hold Last

The last valid output value received by the control unit is continuously and cyclically transmitted to the IO-Link Device.

For proper *Hold Last* behavior the appropriate IOL-Device parameters must also be set to Hold Last.

Replacement Value

If this option is selected, the value entered in the Replacement Value input field described below is continuously and cyclically transmitted to the IO-I ink Device

IO-Link Master Command

The IO-Link Master Command option allows the use of IO-Link-specific mechanisms for valid/invalid output process data. Thus, the device itself determines the behavior

Replacement Value

Replacement Value (Byte 1, enter in decimal):	0
Replacement Value:	0
Replacement Value:	0
Replacement Value (Byte n, enter in decimal):	0

Figure 24: Byte data

Replacement Value (Word 1, e.g. 0x0102 = 258 dec., 0x01 fi	0
Replacement Value:	0
Replacement Value:	0
Replacement Value (Word n,	
e.g. 0x0102 = 258 dec., 0x01 fi	0

Figure 25: Word data

If the "Fail Safe Value(s)" option is set to "Replacement Value", the substitute value(s) entered in this/these input field(s) is/are used.

The value must be entered as a decimal value. Depending on the configured data length, the values must be entered as bytes (0-255) or word decimal values (0-65535) in the order shown.

- ▶ Byte 1 = high order byte (UINT8), in decimal
- ▶ Byte n = low order byte (UINT8), in decimal
- ► Word 1 = high order word (UINT16), in decimal

► Word n = low order word (UINT16), in decimal

"Word" examples: 0x0102 = 258 dec., 0x01 =first byte for IO-Link device, 0x02 =second byte for IO-Link device.

8.4.3 Standardized port parameters

Digital Mode, Ch. B

With this parameter the mode of channel B can be defined. The following modes are available:

- Disabled
- Digital Input
- Digital Output
- Power Supply Output (fed from U_I voltage)

The activated power supply output will be signaled by the white port LED.

Default: Digital Input

Port Diagnostic, Ch. A

The IO-Link Master port diagnostics and the IO-Link Device alarms of type "error" or "warning" can be enabled or disabled over this option.

Default: Enabled

Process Alarm, Ch. A (Device Notifications)

The IO-Link Device alarm notifications can be enabled or disabled with this option. Disabled means, that all notification alarm types from every IO-Link Device will be suppressed by the IO-Link Master. They will be not forwarded by PROFINET alarms to the controller.

Default: Enabled

Configuration Source, Ch. A

PROFINET IO Controller:

The IO-Link Master port configuration will be assigned by the PROFINET IO Controller.

Port and Device Configuration Tool:

(Not supported yet)

The IO-Link Master port configuration will be assigned by an external IO-Link Port and Device Configuration Tool.

Default: PROFINET IO Controller

Input Fraction, Ch. A

If the user configures a sub-slot module with less than the real input data of the device, the IO-Link Master sends as much as possible IO-Link Device input bytes to the PLC inclusive the PQI byte of the sub-slot module. As a consequence, only "0" up to (Device Input Length - 1) octets of the input data of the device can be mapped to the PROFINET process input data of the IO-Link Master. If this option is disabled, a data length mismatch alarm is active in the case of a mismatching input data length. In case of an output data mismatch, a process data mismatch diagnosis will be generated independently of the selected "Input Fraction" setting.

Default: Disabled

Pull/Plug, Ch. A

Enables or Disables Pull/Plug alarms of an IOL-Device (Add/Remove Submodule). A failure or the return of an IO-Link Device can be mapped via PROFINET Plug or Pull alarms. This mapping is independent from any phase such as power-up or start-up.

Plug Alarms:

- -"Ready to Operate" (IOL-Device is ready)
- -"COM Fault" (incorrect device or other problems) IOL-Device started but not ready due to fault.

Pull Alarms:

-"COM Fault" (No IOL-Device)

In the "Disabled" option, channel diagnostics will be generated in case of losing an IO-Link Device.

Default: Enabled

Port Mode, Ch. A

Deactivated:

With the "Deactivated" option, an IO-Link port can be configured for later use. No diagnostics are generated if the IO-Link Device is not connected.

IO-Link - Autostart:

With the "Plug&Play" option no explicit port configuration is needed. Basic assignments such as Validation and Backup (Inspection Level), Port Cycle Time, Vendor ID and Device ID are not required.

IO-Link - Manual:

Explicit port configuration possible for Validation and Backup (Inspection Level), Port Cycle Time, Vendor ID and Device ID. These Parameters are GSD based and can be set over PROFINET engineering system.

Default: IO-Link Autostart

Overview and dependencies of the Port Mode configuration type:

Feature	IO-Link - autostart	IO-Link - manual (GSD)
Access on Process Data (PD)	Yes	Yes
Diagnostics of port & device	Yes	Yes
I&M data (IM0) access	Yes	Yes
Device check (consolidated/real)	No	Yes
Backup & Restore	No	Yes
Device parameterization (PDCT)	No	No
Commissioning (online)	No	No

Table 11: Overview, port mode config types

Validation and Backup, Ch. A

For using the "Validation and Backup" functionality of the IOL-Master, the port mode must be set to "IO-Link - manual".

In dependency of the "Validation and Backup" setting, the entry of the parameters *Vendor ID* and *Device ID* might be obligatory.

No IOL-Device check:

No check of connected *Vendor ID* or *Device ID* and no *Backup and Restore* support of the IOL-Master parameter server

Type compatible IOL-Device (V1.0):

Type compatible according IO-Link specification V1.0

Type compatible IOL-Device (V1.1):

Type compatible according IO-Link specification V1.1, check of *Vendor ID* and *Device ID* by IOL-Master

Type compatible IOL-Device (V1.1) with Backup & Restore:

Type compatible according IO-Link specification V1.1, check of *Vendor ID* and *Device ID* by IOL-Master with *Backup and Restore*. For *Backup and Restore* function, the connected IOL-Device must be type compatible.

Backup (device to master):

A Backup (Upload / from IOL-Device to IOL-Master) is performed when an IO-Link Device is connected and the master does not have any valid data. The parameter data read are permanently stored on the master.

If parameter data are changed on the device during runtime, the device parameter stored on the master can be updated using the ParamDownloadStore (Index 0x0002, Subindex 0x00, Value 0x05) command. This command sets the DS_UPLOAD_REQ flag on the device, and thus IOL-Master executes an upload from IOL-Device.

For each new connection to an IO-Link Device, the master compares the stored parameter data with the

device data. If the function is not locked on the device (Parameter storage locked), the master downloads the stored data to the device in case of detected differences.

With the Backup function, the IO-Link Master can be replaced.

Restore (master to device):

Parameter data can only be transferred to an IO-Link Device if they exist on the IOL-Master parameter server and are usable for the device. When an IOL-Device is connected, the master compares the stored parameter data with the IOL-Device data. If the function is not locked on the device (Parameter storage locked), the master downloads the stored data to the device in case of detected differences.

If the master does not have a device parameter set stored, nothing happens. With the Restore function, the IO-Link Device can be replaced.

Default: No IOL-Device check

Action	IO-Link Master State	IO-Link Device State
Backup	Invalid Data (Or Cleared)	Upload flag active (Valid Data)
Backup	Invalid Data (Or Cleared)	Upload flag not active & Valid Data
Backup	Valid Data	Upload flag active & Valid Data
Restore	Valid Data	Upload flag not active (Data Equal)



Attention: An IO-Link Device sets the "upload flag" self-dependent, if parameter were written in block mode to the IO-Link Device.

Port Cycle Time, Ch. A (Port Mode "IO-Link - manual" required)

As fast as possible:

The IO-Link Master uses the max. supported IOL-Device update cycle time limited by the max.

supported IOL-Master cycle time for the cyclic IO data update between IOL-Master and IOL-Device.

1.6, 3.2, 4.8, 8, 20.8, 40, 80, 120 ms:

The cycle time can be set manually to the provided options. This option can be used e.g. for IOL-Device modules which are connected over inductive couplers. Inductive couplers are normally the bottleneck in the update cycle time between IOL-Master and IOL-Device. In this case, please refer to the data sheet of the inductive coupler.

Default: As fast as possible

Vendor ID, Ch. A (Port Mode "IO-Link - manual" required)

The Vendor ID of the connected IOL-Device used can be entered as a decimal value [0 ... 65535] and will be in used in dependency of the Validation and Backup settings for the validation of the type compatibility.

Default: 0

Device ID, Ch. A (Port Mode "IO-Link - manual" required)

The *Device ID* of the connected IOL-Device can be entered as a decimal value [0 ... 65535] and will be in used in dependency of the *Validation and Backup* settings for the validation of the type compatibility.

Default: 0

8.5 IO-Link Device Parameterization

8.5.1 SIEMENS IO-Link library

The SIEMENS "IO_LINK_DEVICE" function block (FB50001) can both acyclic write parameters and read parameters, I/O data and diagnostic data of an IOL-Device connected to the IO-Link Master.

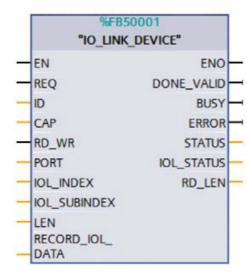


Figure 26: "IO LINK DEVICE" FB in STEP 7 V15.1

IOL-Device data are uniquely addressed via the index and the sub-index and can be accessed or written via the hardware identifier of the status/ control module (ID) inputs, the client access point (CAP = 0xB400) and the corresponding IO-Link port (PORT: 1 - 8 for IO-Link ports).

The following TIA project shows the used hardware identifier of the submodule for port X1 (282) with Write/Read examples. Alternatively, the hardware identifier of the Status/Control module can also be used (281 in this example).

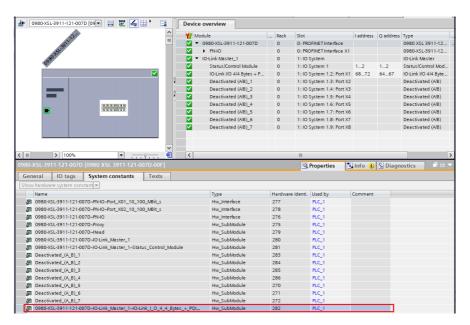


Figure 27: TIA project: Write/Read example with FB50001

8.5.1.1 SIEMENS function block FB50001 - write example

The following is a write example for an IOL-Device on port X1 at the application tag parameter (IOL_INDEX=24). The input data are in decimal. The write data are in hexadecimal. The written value is "test" (= 74 / 65 / 73 / 74 in HEX).

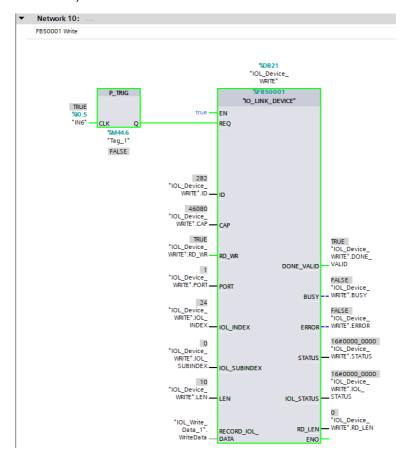


Figure 28: write example for FB50001

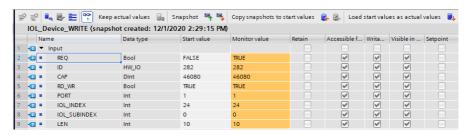


Figure 29: Input control data for write request via FB50001

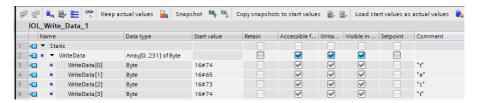


Figure 30: Data to be written via FB50001

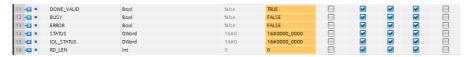


Figure 31: Output status for write request via FB50001

8.5.1.2 SIEMENS function block FB50001 - read example

The following is a read example for an IOL-Device on port X1 at the application tag parameter (IOL_INDEX=24). The input data are in decimal. The read data are in hexadecimal. The previously written value "test" (= 74 / 65 / 73 / 74 in HEX) will be read here.

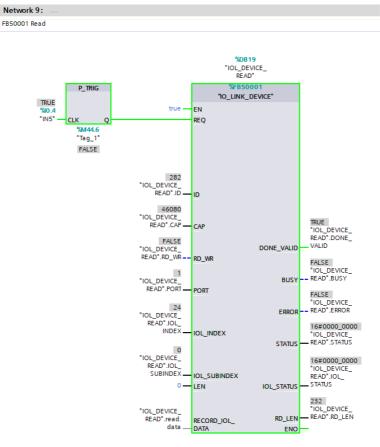


Figure 32: Read example for FB50001



Figure 33: Control data for read request via FB50001

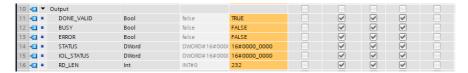


Figure 34: Staus data for read request via FB50001

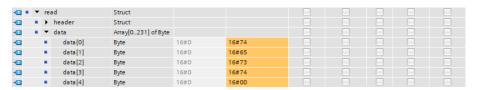


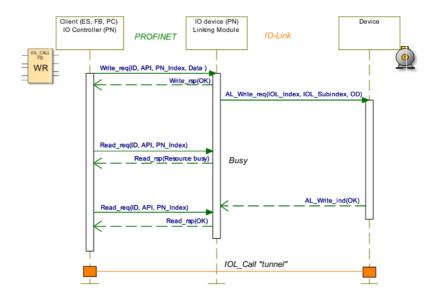
Figure 35: Read data from application tag of the IO-Link Device via FB50001

8.5.2 SIEMENS WRREC and RDREC

The Reading and Writing Parameters from the PLC over the IOL-Master to the connected IOL-Device modules can also be handled by using the SIEMENS Function Blocks SFB52/RDREC and SFB53/WREC.

8.5.2.1 Write sequence

The following figure shows the sequence of WRREC and RDREC calls for writing data:



The following table shows the sequence with example data compared to the *FB50001*. The *FB50001* uses the WRREC and RDREC blocks also internally:

FB50001 Call	WRREG	WRREC				RDREC	Response	
ID (address proxy)	ID (addı	ress proxy)			ID (address proxy)			
CAP	PN_Ind	ex = 0xB400)		PN_Index = 0xB400			
WR	Data Header	Function (fixed)	0x08	Unsigned8		Data Header	Function (fixed)	0x08
Port		Port	1-8	Unsigned8			Port	1-8
		FI_Index (Fixed)	0xFE4A	Unsigned16			FI_Index (Fixed)	0xFE4A
		Control/ Status (→Write)	0x02	Unsigned8			Control/Status	0x00
IOL-Index		IOL- Index (0-32767; 65535)	0x	Unsigned16			IOL-Index (0-32767; 65535)	0x
IOLSubIndex		IOL-Sub- Index (0-255)	0x00	Unsigned8			IOL-Sub- Index (0-255)	0x00
IOL-Data		WR-Data					Data (opt. Error PDU)	

Table 12: WRREC ID



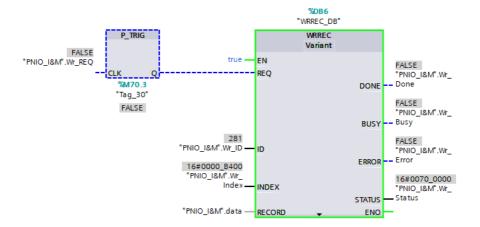
Attention: Unsigned16 values must be entered in Big Endian format for PROFINET.

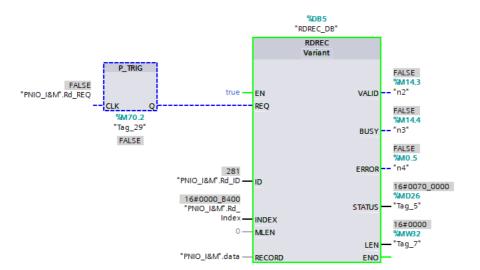
Bit 7	Bit 6	Bit 5	Bit 4	Bit3	Bit2	Bit 1	Bit 0	Definition of Control octets
0	0	0	0	0	0	0	0	Cancel / Release IOL_CALL
0	0	0	0	0	0	0	1	IDLE Sequence
0	0	0	0	0	0	1	0	Write On-request Data or Port function
0	0	0	0	0	0	1	1	Read On-request Data
Other codings							Reserved	

Table 13: Control Parameter

Bit 7	Bit 6	Bit 5	Bit 4	Bit3	Bit2	Bit 1	Bit 0	Definition of Status octets
0	0	0	0	0	0	0	0	Done / Transfer terminated
0	0	0	0	0	0	0	1	IDLE Sequence
1	0	0	0	0	0	0	0	IOL_Error PDU
Other codings						Reserved		

Table 14: Status Parameter





•		Wr_REQ	Bool	false	FALSE
-		Wr_Index	DWord	16#0	16#0000_B400
•		Wr_ID	HW_IO	0	281
•		Wr_Done	Bool	false	FALSE
411 •		Wr_Busy	Bool	false	FALSE
-11		Wr_Error	Bool	false	FALSE
411 •		Wr_Status	DWord	16#0	16#0000_0000
-1		Wr_Len	UInt	0	0
1	•	data	Array[039] of Byte		
1	•	data[0]	Byte	16#0	16#08
40		data[1]	Byte	16#0	16#05
- ■		data[2]	Byte	16#0	16#FE
4Ⅲ		data[3]	Byte	16#0	16#4A
- ■		data[4]	Byte	16#0	16#02
4Ⅲ	•	data[5]	Byte	16#0	16#00
- 111	•	data[6]	Byte	16#0	16#18
4Ⅲ	•	data[7]	Byte	16#0	16#00
- 111	•	data[8]	Byte	16#0	16#54
- 111	•	data[9]	Byte	16#0	16#45
4Ⅲ	•	data[10]	Byte	16#0	16#53
- 111	•	data[11]	Byte	16#0	16#54
- 111	•	data[12]	Byte	16#0	16#00
- ■	•	data[13]	Byte	16#0	16#00
4Ⅲ	•	data[14]	Byte	16#0	16#00
- ■	•	data[15]	Byte	16#0	16#00
-11	•	data[16]	Byte	16#0	16#00
4Ⅲ	•	data[17]	Byte	16#0	16#00

Figure 36: Example of data before writing

			_		
•		Wr_REQ	Bool	false	TRUE
■ 🖦		Wr_Index	DWord	16#0	16#0000_B400
•		Wr_ID	HW_IO	0	281
•		Wr_Done	Bool	false	FALSE
•		Wr_Busy	Bool	false	FALSE
•		Wr_Error	Bool	false	FALSE
•		Wr_Status	DWord	16#0	16#0000_0000
•		Wr_Len	UInt	0	0
•	•	data	Array[039] of Byte		
•	•	data[0]	Byte	16#0	16#08
€	•	data[1]	Byte	16#0	16#05
•	•	data[2]	Byte	16#0	16#FE
€		data[3]	Byte	16#0	16#4A
•		data[4]	Byte	16#0	16#02
•		data[5]	Byte	16#0	16#00
•	•	data[6]	Byte	16#0	16#18
•		data[7]	Byte	16#0	16#00
•	•	data[8]	Byte	16#0	16#54
•		data[9]	Byte	16#0	16#45
•	•	data[10]	Byte	16#0	16#53
•		data[11]	Byte	16#0	16#54
•	•	data[12]	Byte	16#0	16#00
•		data[13]	Byte	16#0	16#00
•		data[14]	Byte	16#0	16#00
•		data[15]	Byte	16#0	16#00
•		data[16]	Byte	16#0	16#00
•		data[17]	Byte	16#0	16#00

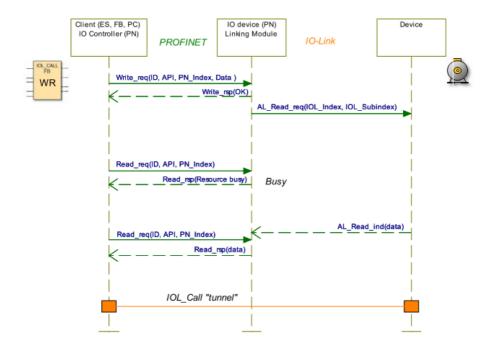
Figure 37: Example of data after writing

	Na	me	Data type	Start value	Monitor value
•	•	Static			
1	•	Rd_REQ	Bool	false	TRUE
€11		Rd_Index	DWord	16#0	16#0000_B400
€	•	Rd_ID	HW_IO	0	281
€	•	Rd_Valid	Bool	false	FALSE
411		Rd_Busy	Bool	false	FALSE
€	•	Rd_Error	Bool	false	FALSE
1	٠	Rd_Status	DWord	16#0	16#0000_0000
1		Rd_Len	UInt	0	0
40	•	▼ data	Array[039] of Byte		
1		data[0]	Byte	16#0	16#08
€		data[1]	Byte	16#0	16#05
1		data[2]	Byte	16#0	16#FE
€		data[3]	Byte	16#0	16#4A
1		data[4]	Byte	16#0	16#00
1		data[5]	Byte	16#0	16#00
1		data[6]	Byte	16#0	16#18
411		data[7]	Byte	16#0	16#00
1		data[8]	Byte	16#0	16#54
1		data[9]	Byte	16#0	16#45
411		data[10]	Byte	16#0	16#53
€11		data[11]	Byte	16#0	16#54
411		data[12]	Byte	16#0	16#00
€		data[13]	Byte	16#0	16#00
40		data[14]	Byte	16#0	16#00
40		data[15]	Byte	16#0	16#00
1		data[16]	Byte	16#0	16#00
1		data[17]	Byte	16#0	16#00

Figure 38: Read data after writing

8.5.2.2 Read sequence

The following figure shows the sequence of WRREC and RDREC calls for reading data:



The following table shows the sequence with example data compared to the FB50001. The FB50001 uses the WRREC and RDREC blocks also internally:

FB50001 Call	WRREC	;			RDREC	RDREC	Response	
ID (address proxy)	ID (addr	ess proxy)			ID (address proxy)			
CAP	PN_Inde	ex = 0xB400)		PN_Index = 0xB400			
WR	Data Header	Function (fixed)	0x08	Unsigned8		Data Header	Function (fixed)	0x08
Port		Port	1-8	Unsigned8			Port	1-8
		FI_Index (Fixed)	0xFE4A	Unsigned16			FI_Index (Fixed)	0xFE4A
		Control/ Status (→Read)	0x03	Unsigned8			Control/ Status	0x00
IOL-Index		IOL- Index (0-32767; 65535)	0x	Unsigned16			IOL-Index (0-32767; 65535)	0x
IOLSubIndex		IOL-Sub- Index (0-255)	0x00	Unsigned8			IOL-Sub- Index (0-255)	0x00
IOL-Data		-					Data (opt. Error PDU)	

Table 15: RDREC ID



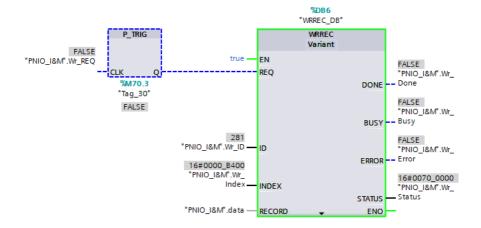
Attention: Unsigned16 values must be entered in Big Endian format for PROFINET.

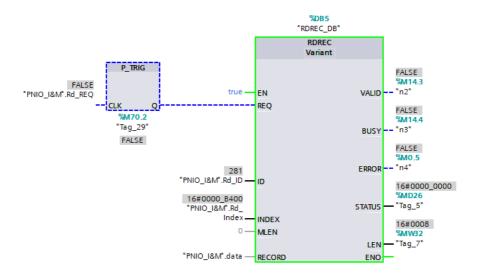
Bit 7	Bit 6	Bit 5	Bit 4	Bit3	Bit2	Bit 1	Bit 0	Definition of Control octets
0	0	0	0	0	0	0	0	Cancel / Release IOL_CALL
0	0	0	0	0	0	0	1	IDLE Sequence
0	0	0	0	0	0	1	0	Write On-request Data or Port function
0	0	0	0	0	0	1	1	Read On-request Data
Other codings							Reserved	

Table 16: Control Parameter

Bit 7	Bit 6	Bit 5	Bit 4	Bit3	Bit2	Bit 1	Bit 0	Definition of Status octets
0	0	0	0	0	0	0	0	Done / Transfer terminated
0	0	0	0	0	0	0	1	IDLE Sequence
1	0	0	0	0	0	0	0	IOL_Error PDU
Other codings							Reserved	

Table 17: Status Parameter





- ▼	St	atic			
•	50	Rd_REQ	Bool	false	FALSE
a		Rd_Index	DWord	16#0	16#0000 B400
-		Rd ID	HW_IO	0	281
-		Rd Valid	Bool	false	FALSE
-		Rd_Busy	Bool	false	FALSE
-		Rd Error	Bool	false	FALSE
		Rd_Status	DWord	16#0	16#0000 0000
-		Rd_Len	UInt	0	0
		Wr REQ	Bool	false	FALSE
		Wr Index	DWord	16#0	16#0000_B400
		Wr ID	HW IO	0	281
		Wr_Done	Bool	false	FALSE
		Wr Busy	Bool	false	FALSE
		Wr_Error	Bool	false	FALSE
		Wr_Status	DWord	16#0	16#0000 0000
		Wr Len	UInt	0	0
		data	Array[039] of Byte	0	· ·
		data[0]	Byte	16#0	16#08
- T	i	data[1]	Byte	16#0	16#05
	i	data[2]	Byte	16#0	16#FE
40	i	data[3]	Byte	16#0	16#4A
	i	data[4]	Byte	16#0	16#03
	i	data[5]	Byte	16#0	16#00
	i	data[6]	Byte	16#0	16#18
	i	data[7]	Byte	16#0	16#00
	i	data[8]	Byte	16#0	16#00
	ī	data[9]	Byte	16#0	16#00
	i	data[10]	Byte	16#0	16#00
•	i	data[11]	Byte	16#0	16#00
- T	i	data[12]	Byte	16#0	16#00
•	i	data[13]	Byte	16#0	16#00
- T	ī	data[14]	Byte	16#0	16#00
- T	i	data[15]	Byte	16#0	16#00
- T	i	data[16]	Byte	16#0	16#00
- T	ī	data[17]	Byte	16#0	16#00
-	-	uata[1/]	byte	10#0	10#00

Figure 39: Example of data before reading

- ■	Wr_REQ	Bool	false	TRUE
- ■	Wr_Index	DWord	16#0	16#0000_B400
	Wr_ID	HW_IO	0	281
- ■	Wr_Done	Bool	false	FALSE
- ■	Wr_Busy	Bool	false	FALSE
- ■	Wr_Error	Bool	false	FALSE
- ■	Wr_Status	DWord	16#0	16#0000_0000
- ■	Wr_Len	UInt	0	0
■ ▼	data	Array[039] of Byte		
■ •	data[0]	Byte	16#0	16#08
•	data[1]	Byte	16#0	16#05
•	data[2]	Byte	16#0	16#FE
-	data[3]	Byte	16#0	16#4A
40	data[4]	Byte	16#0	16#03
40	data[5]	Byte	16#0	16#00
40	data[6]	Byte	16#0	16#18
40	data[7]	Byte	16#0	16#00
40	data[8]	Byte	16#0	16#00
40	data[9]	Byte	16#0	16#00
40	data[10]	Byte	16#0	16#00
40	data[11]	Byte	16#0	16#00
■ •	data[12]	Byte	16#0	16#00
40 •	data[13]	Byte	16#0	16#00
40 •	data[14]	Byte	16#0	16#00
40 •	data[15]	Byte	16#0	16#00
40 •	data[16]	Byte	16#0	16#00
-	data[17]	Byte	16#0	16#00

Figure 40: Example of data after reading

	Nai	me	Data type	Start value	Monitor value
1	•	Static			
1	•	Rd_REQ	Bool	false	TRUE
€00	٠	Rd_Index	DWord	16#0	16#0000_B400
4 □	•	Rd_ID	HW_IO	0	281
€11	•	Rd_Valid	Bool	false	FALSE
€11	٠	Rd_Busy	Bool	false	FALSE
€00	•	Rd_Error	Bool	false	FALSE
€11	٠	Rd_Status	DWord	16#0	16#0000_0000
€00	•	Rd_Len	UInt	0	0
€		▼ data	Array[039] of Byte		
€11		data[0]	Byte	16#0	16#08
■		data[1]	Byte	16#0	16#05
€		data[2]	Byte	16#0	16#FE
€11		data[3]	Byte	16#0	16#4A
€		data[4]	Byte	16#0	16#00
1		data[5]	Byte	16#0	16#00
1		data[6]	Byte	16#0	16#18
1		data[7]	Byte	16#0	16#00
1		data[8]	Byte	16#0	16#54
1		data[9]	Byte	16#0	16#45
1		data[10]	Byte	16#0	16#53
1		data[11]	Byte	16#0	16#54
4 □		data[12]	Byte	16#0	16#00
1		data[13]	Byte	16#0	16#00
1		data[14]	Byte	16#0	16#00
4 ■		data[15]	Byte	16#0	16#00
4 ■		data[16]	Byte	16#0	16#00
4 ■		data[17]	Byte	16#0	16#00

Figure 41: Read data after reading

8.5.2.3 Error PDU for the Read/Write sequence

Offset	Parameter	Content	Data type
0	Port Error	Error Codes detected by the Linking Module or Client	Unsigned16
2	Error Code	IO-Link Error codes according AL_Read/ AL_Write services	Unsigned8
3	Additional Code	IO-Link Error codes according AL_Read/ AL_Write services	Unsigned8

Table 18: Error PDU

Port Error Code	Definition	Coding	Originator
No error	No error detected	0x0000	Server
Reserved	-	0x0001 to 0x06FFF	-
IOL_CALL conflict	Inconsistent Header information	0x7000	Server and/or Client
Incorrect IOL_CALL	Inconsistent Header information (send-/response)	0x7001	Server and/or Client
Port blocked	Port temporary not available	0x7002	Server
Reserved	-	0x7003 to 0x7FFF	-
Timeout	No correct termination of IOL_CALL (Resource Busy detection)	0x8000	Client
Invalid port number	Invalid port Number or port not supported	0x8001	Client and/or Server
Invalid IOL_Index	Invalid Index	0x8002	Client
Invalid IOL_Subindex	Invalid Subindex	0x8003	Client
No Device	No device	0x8004	Client
Reserved	-	0x8005 to 0x8051	-
RDREC Fault	Fault during Read record invocation	0x8052	Client
WRREC Fault	Fault during Write record invocation	0x8053	Client
Unexpected Error	Unspecific Error detected	0x8054	Client
Port Function error	Port function failed	0x8055	Server

Port Error Code	Definition	Coding	Originator
Port Function not available	Port function is not available (in this state)	0x8056	Server
Port Function not supported	Port function (for this port) not supported	0x8057	Server
Manu	Manufacturer specific	0x8058 to 0xFFFF	Server

Table 19: Port Error of Error PDU

8.6 Media Redundancy Protocol (MRP)

Redundant PROFINET communication can be implemented with the LioN-X devices via a ring topology without the use of additional switches. A MRP redundancy manager terminates the ring, detects individual failures, and transmits the data packets on the redundant path in case of error.

The following conditions must be met to use MRP:

- All devices must support MRP.
- MRP must be enabled on all devices.
- Connections to the devices are only possible via the ring ports. A mesh topology is not permissible.
- A max. of 50 devices are permissible in the ring.
- All devices share the same redundancy domain.
- One device must be configured as the redundancy manager.
- All other devices must be configured as redundancy clients.
- Prioritized boot (FSU) is permissible.
- ➤ The response monitoring time of all devices must be greater than the reconfiguration time (typically 200 ms, min. 90 ms for LioN-X devices).
- ▶ It is recommended to use automatic network settings on all devices.

The following figures show a possible MRP ring configuration. The PLC is used as the redundancy manager while all other devices are clients. To detect an individual failure, it is advisable to use the diagnostics alerts.

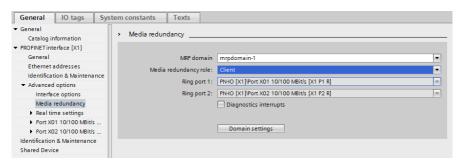


Figure 42: Example of setting up an MRP redundancy client in TIA Portal®

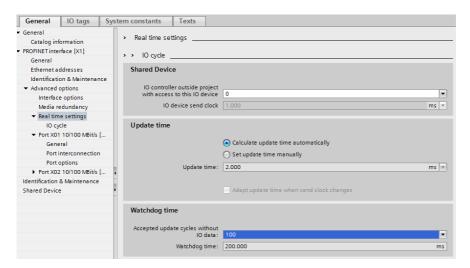


Figure 43: Example of setting up the Watchdog time monitoring in TIA Portal® for using MRP

8.7 Identification & maintenance functions (I&M)

The PROFINET IO-Link Master has the ability to uniquely identify the devices installed in the system via an electronic nameplate. This device-specific data can be read acyclic by the user at any time. Furthermore, the installation date, location code and further descriptions can be stored in the device during installing the system. The I&M functions provide the following functionality.

8.7.1 Supported I&M features

8.7.1.1 I&M data of the PN-IO Device

For reading (I&M 0 - 3) and writing (I&M 1 - 3) I&M data, the appropriate Hardware identifier for Slot **0: PROFINET Interface X1** must be chosen:

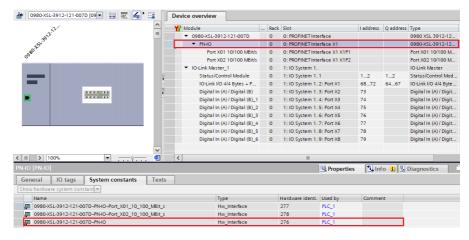


Figure 44: TIA Portal® hardware identifier of PROFINET interface for I&M 0-3 RDREC/WRREC

The device-specific I&M features can be read (0-3) or written (1-3) via slot 0. The specified index is used for mapping the data sets.

Data object	Length [byte]	Access	Default value / Description
MANUFACTURER_ID	2	Read	0x016A (Belden Deutschland GmbH)
ORDER_ID	20	Read	Order number of module in ASCII
SERIAL_NUMBER	16	Read	Defined in production process in ASCII
HARDWARE_REVISION	2	Read	Hardware revision of device
SOFTWARE_REVISION	4	Read	Software revision of device
REVISION_COUNTER	2	Read	Incremented for every statically stored parameter change on IO-Link Master (e.g., device name or IP address)
PROFILE_ID	2	Read	0xF600 (Generic device)
PROFILE_SPECIFIC_TYPE	2	Read	0x0003 (IO modules)
IM_VERSION	2	Read	0x0101 (I&M Version 1.1)
IM_SUPPORTED	2	Read	0x000E (I&M 1 3 & 5 is supported)

Table 20: I&M 0 (Slot 0: PROFINET Interface X1, Index 0xAFF0)

Data object	Length [byte]	Access	Default value / Description
TAG_FUNCTION	32	Read/ Write	0x20 ff. (empty)
TAG_LOCATION	22	Read/ Write	0x20 ff. (empty)

Table 21: I&M 1 (Slot 0: PROFINET Interface X1, Index 0xAFF1)

Data object	Length [byte]	Access	Default value / Description
INSTALLATION_DATE	16	Read/ Write	0x20 ff. (empty); Supported data format is a visible string with a fix length of 16 byte; "YYYY-MM-DD hh:mm" or "YYYY-MM-DD" filled with blank spaces

Table 22: I&M 2 (Slot 0: PROFINET Interface X1, Index 0xAFF2)

Data object	Length [byte]	Access	Default value / Description
DESCRIPTOR	54	Read/ Write	0x20 ff. (empty)

Table 23: I&M 3 (Slot 0: PROFINET Interface X1, Index 0xAFF3)

8.7.1.2 I&M data of the IOL-Master proxy (Status/Control Module)

For reading *I&M 0* data, the appropriate hardware identifier for Slot 1: **IO System 1.1** must be chosen:

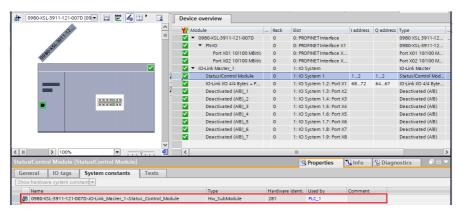


Figure 45: Hardware identifier of the Status/Control Module for RDREC "IO System 1"

Data object	Length [byte]	Access	Default value / Description
MANUFACTURER_ID	2	Read	0x016A (Belden Deutschland GmbH)
ORDER_ID	20	Read	Order number of module in ASCII
SERIAL_NUMBER	16	Read	Defined in production process in ASCII
HARDWARE_REVISION	2	Read	Hardware revision of device
SOFTWARE_REVISION	4	Read	Software revision of device
REVISION_COUNTER	2	Read	Incremented for every statically stored parameter change on IO-Link Master (e.g., device name or IP address)
PROFILE_ID	2	Read	0x4E01 (IOL-Master proxy)
PROFILE_SPECIFIC_TYPE	2	Read	0x0000 (unspecified)
IM_VERSION	2	Read	0x0101 (I&M Version 1.1)
IM_SUPPORTED	2	Read	0x0000

Table 24: I&M 0 (Slot 1: IO System 1.1, Index 0xAFF0)

8.7.1.3 I&M data of the IOL-Device proxy

The IO-Link Device-specific *I&M 0* and *I&M 5* data can be read via slot 1 and the appropriate sub-slot (1.2/Port X1 ...1.9/Port X8). The specified index is used for mapping the data sets. Only data not equal to zero are received if a connection to an IO-Link Device can be established.

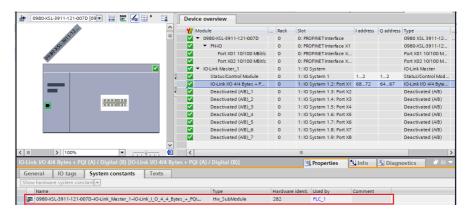


Figure 46: Hardware identifier of the Status/Control module for RDREC "IO System 1.2"

I&M0 data	Octets	Data type	Mapping rules
VendorID	2	Unsigned16	IO-Link Direct parameter page 1: VendorID. Direct mapping, for example "0x136". Exceptions: 1 → 93; 26 → 257; 87 → 467.
OrderID	20	Visible String	"Product Name" or "DeviceID".
IM_Serial_Number	16	Visible String	Insert SerialNumber of Device (IO-Link Index 21). If it is not available set to "Not accessible".
IM_Hardware_Revision	2	Unsigned8	Set to 0x0000 (Default value)
IM_Software_Revision	4	Char,3 x Unsigned8	Set to V0.0.0 (official release but not detectable)
IM_RevisionCounter	2	Unsigned16	Set to "0" (0x0000)
IM_Profile_ID	2	Unsigned16	IO-Link (API = 0x4E01)
IM_Profile_Specific_Type	2	Unsigned16	Set to "0" (0x0000)
IM_Version	2	2 x Unsigned8	Octet 1 (MSB): set to 0x01 Octet 2 (LSB): set to 0x00
IM_Supported	2	Unsigned16 (Bit Array)	Profile specific I&M: 0x0000 (Bit 0 for I&M0 is always 0)

Table 25: I&M 0 (Slot 1: IO System 1.2 - 1.9, Index 0xAFF0)

I&M5 data	Octets	Data type	Mapping rules
IM_Annotation	64	String (UTF8)	"IO-Link Devices"
IM_OrderID	64	Visible String	"Product Name" or "DeviceID".
IM_VendorID	2	Unsigned16	"VendorID"
IM_Serial_Number	16	Visible String	Insert SerialNumber of device (IO-Link Index 21). If it is not available, set to "Not accessible".
IM_Hardware_Revision	2	Unsigned8	Set to 0x0000 (default value)
IM_Software_Revision	4	Char,3 x Unsigned8	Set to V0.0.0 (official release but not detectable)

Table 26: I&M 5 (Slot 1: IO System 1.2 - 1.9, Index 0xAFF5)

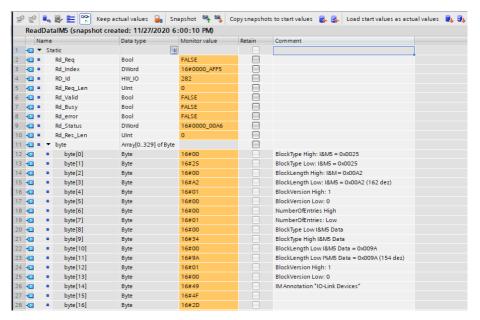


Figure 47: Read example I&M5 on port X1 with connected IOL-Device

8.7.2 Reading and writing I&M data

In its standard library, SIEMENS offers TIA Portal® system function modules that allow I&M data to be read and written. A data set contains a 6-byte *BlockHeader* and the I&M record.

The data requested on reading, or the data to be written thus only start after the existing header. For writing, the header content must additionally be taken into account. Table 27: Data set with BlockHeader and I&M Record on page 104 shows the structure of a data set.

- ► For reading I&M 0..3, the RDREC block must be configured with LEN = 6 Byte Block Header + I&M data length.
- ► For reading I&M 5, the RDREC block must be configured with LEN = 6
 Byte Block Header + 8 Byte I&M + I&M data length.

Data object	Length [byte]	Data type	Coding	Description
BlockType	2	Word	I&M 0: 0x0020 I&M 1: 0x0021 I&M 2: 0x0022 I&M 3: 0x0023 I&M 5: 0x0025	BlockHeader
BlockLength	2	Word	I&M 0: 0x0038 I&M 1: 0x0038 I&M 2: 0x0012 I&M 3: 0x0038 I&M 5: 0x0098	
BlockVersionHigh	1	Byte	0x01]
BlockVersionLow	1	Byte	0x00	1
I&M Data	I&M 0: 54 I&M 1: 54 I&M 2: 16 I&M 3: 54 I&M 5: 152	Byte		I&M Record

Table 27: Data set with BlockHeader and I&M Record

8.7.2.1 I&M Read Record

I&M data can be read via the standard RDREC (SFB52) function block in the **Siemens PLC**. The logical address of the slot/sub-slot (ID) and the I&M index (INDEX) must be used as handover parameters. The return parameters show the length of the I&M data received, and contain a status or error message.

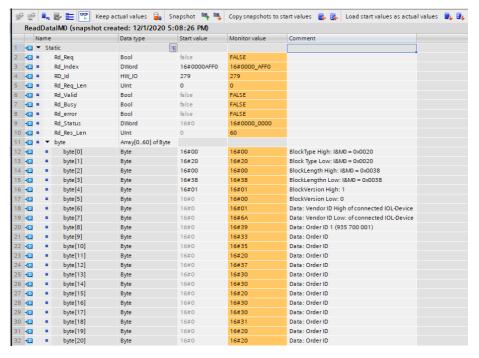


Figure 48: Read example I&M0 of PROFINET IO device

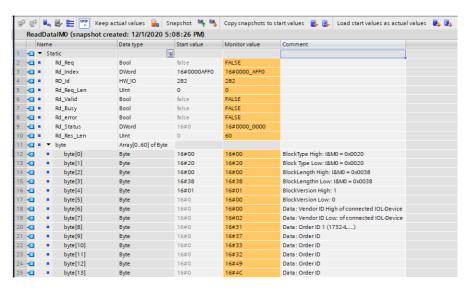


Figure 49: Read example I&M0 on port X1 with connected IOL-Device

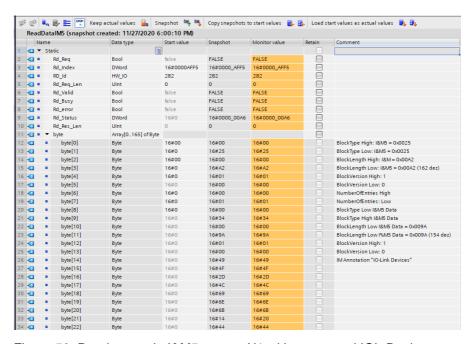


Figure 50: Read example I&M5 on port X1 with connected IOL-Device

8.7.2.2 I&M Write Record

I&M data can be written via the standard WRREC (SFB53) function block in the **Siemens PLC**. The logical address of the slot/sub-slot (ID), the I&M index (INDEX) and the data length (LEN) must be used as handover parameters. The return parameters contain a status or error message.

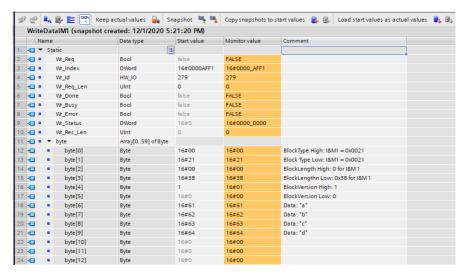
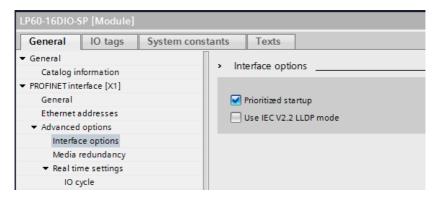


Figure 51: Example of a completed I&M1 write action of a PROFINET IO device

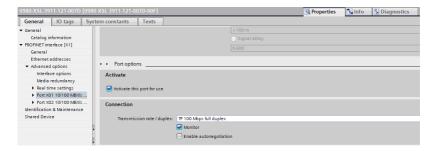
8.8 Fast Start-Up (FSU) / Prioritized Start-Up

The LioN-X devices with Fast Start-Up (FSU) support an optimized system start-up. This guarantees a faster restart after the power supply is restored.

Fast Start-Up can be activated for the LioN-X devices with PROFINET interface [X1] > Advanced options > Interface options over Prioritized start-up.



For better FSU performance, the transmission settings of ports X01 and X02 should be set to:





Attention: The settings for the local and the partner port must be identical.

Measured boot times

PROFINET FSU time: 1)

< 2200 ms

Start time with FSU activated:²⁾

0980 XSL... variants: ~2400 ms

0980 LSL... variants: ~12000 ms

Start time without FSU activated:²⁾

0980 XSL... variants: ~5400 ms

0980 LSL... variants: ~16000 ms

- 1) Measured according to specification: Internal switch is able to forward telegrams.
- 2) PLC reads one digital input and sets one digital output on IO-Link Master after power-up of the DUT (IO-Link Master). PLC is connected directly to DUT port X01 without any additional switch between PLC and DUT.

9 Process data assignment

The LioN-X IO-Link Masters use a modular device model. Slot 1/sub-slot 1 contains the Status/Control module of the IO-Link Master. The module has 2 bytes of input data and 2 bytes of output data. It is always statically configured when selecting a LioN-X IO-Link Master from the GSD file.

The IO-Link ports use the following sub-slots 2 through 9 of slot 1; they can have a different operating mode and data length depending on the configuration.

9.1 Process data Status/Control Module, I/O system 1.1

The Status/Control Module has one UINT16 for digital input data and one UINT16 for digital output data.

Status Data (input)

The input UINT16 contains the status of the digital inputs. For the digital A-channel inputs, the data are also available in the input byte of the appropriate sub-slot module.

Control Data (output)

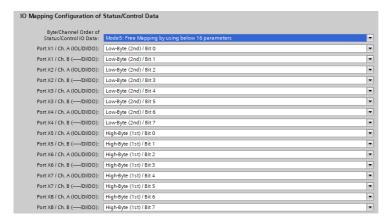
The output UINT16 contains the control bits for the digital outputs of the B-channels.

For controlling the digital A-Channels, the output **Byte** 1/Bit 0 of the appropriate sub-slot module must be used. Over the **General Device Settings** parameter **Digital Out Ch. A Controlled By: Status/Control Module** the control can be switched to the *Control Bits*. In this case, the outputs cannot be controlled by the sub-slot output **Byte 1/Bit 0**.

The digital output can be controlled only by one data source.

Parameter Dependencies for Digital-IO data mapping

Please refer to chapter I/O mapping configuration of Status/Control data on page 54 for the Bit Mapping



9.1.1 Status/Control data with Bit Mapping

The following bit mapping status/control examples are exclusively valid for LioN-X 0980 XSL 3912-121-007D-00F. For details on bit mapping configuration, see chapter I/O mapping configuration of Status/Control data on page 54.

Key

X1A = Port 1, Channel A

9.1.1.1 Mode 1

(example for 0980 XSL 3912-121-007D-00F)

I/O	Status/ Control	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Status/ Control	UINT16 High-B (1st)	X8B	X8A	X7B	X7A	X6B	X6A	X5B	X5A
Slot 1.1	UINT16 Low-B (2nd)	X4B	X4A	ХЗВ	ХЗА	X2B	X2A	X1B	X1A

Table 28: Digital Input/Output Mapping Mode 1

9.1.1.2 Mode 2

(example for 0980 XSL 3912-121-007D-00F)

I/O	Status/ Control	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Status/ Control	UINT16 High-B (1st)	X4B	X4A	ХЗВ	ХЗА	X2B	X2A	X1B	X1A
Slot 1.1	UINT16 Low-B (2nd)	X8B	X8A	X7B	X7A	X6B	X6A	X5B	X5A

Table 29: Digital Input/Output Mapping Mode 2

9.1.1.3 Mode 3

(example for 0980 XSL 3912-121-007D-00F)

I/O	Status/ Control	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Status/ Control Slot 1.1	UINT16 High-B (1st)	X8B	X7B	X6B	X5B	X4B	ХЗВ	X2B	X1B
310(1.1	UINT16 Low-B (2nd)	X8A	X7A	X6A	X5A	X4A	ХЗА	X2A	X1A

Table 30: Digital Input/Output Mapping Mode 3

9.1.1.4 Mode 4

(example for 0980 XSL 3912-121-007D-00F)

I/O	Status/ Control	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Status/ Control	UINT16 High-B (1st)	X8A	X7A	X6A	X5A	X4A	ХЗА	X2A	X1A
Slot 1.1	UINT16 Low-B (2nd)	X8B	X7B	X6B	X5B	X4B	ХЗВ	X2B	X1B

Table 31: Digital Input/Output Mapping Mode 4

9.1.1.5 Mode 5

The mapping for this mode depends on the user settings.

9.1.1.6 PROFIN	NET cha	annel d	iagnost	ics ma	pping

Port	X8	X7	X6	X5	X4	X3	X2	X1
I/O Pin	2/4	2/4	2/4	2/4	2/4	2/4	2/4	2/4
I/O Channel	B/A							
PN Diagn. Channel	8	7	6	5	4	3	2	1

Table 32: PROFINET channel diagnostics mapping

9.2 Process data IO-Link ports, Slot 1.2 – 1.9

The process data lengths of the IO-Link ports in COM mode depend on the IO-Link port configurations X1 - X8. Data lengths between 1 - 33 bytes of input data and/or 1 - 32 bytes of output data are configurable.

The data content can be taken from the descriptions of the IO-Link Devices. If a precise data length is not available for the IO-Link Device configuration, always select the next larger data length.

The last byte of the port input data contains the PQI byte (Port Qualifier Information). This byte is added to the IOL-Device input data by the IOL-Master.

Ch. A configuration as Digital Input

If the Port is configured as digital input, the port data length is one byte and the digital input status will be set on bit 0. The digital input status will also be mapped to the status bytes of the Status/Control Module.

The mapping mode selected for the Status/Control Module has no influence on the process data of the IO-Link ports.

INPUT	Input	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0			
Slot 1.2	X1 Byte 1 – 33		▶ If the IO-Link Port is in "Digital-In" Mode, the									
Slot 1.3	X2 Byte 1 – 33	(Channel A, Pin 4) will be set in Bit 0 of Byte 1. In this cas PQI Byte is available.						case no				
Slot 1.4	X3 Byte 1 – 33	► The	e last Byt	e contair	s the PC	l (Port Q	ualifier Ir	nformatio	n).			
Slot 1.5	X4 Byte 1 – 33	7										
Slot 1.6	X5 Byte 1 – 33	<u> </u>										
Slot 1.7	X6 Byte 1 – 33											
Slot 1.8	X7 Byte 1 – 33											
Slot 1.9	X8 Byte 1 – 33											

Table 33: Input data: Sub-slots 1.2 – 1.9

Bit	Acronym	Short Description	Value	Description
0	-	Reserved	0	Reserved
			_	-
1	-	Reserved	0	Reserved
			-	-
2	NewParam New parameter		0	Not supported yet, don't evaluate this bit!
			1	Not supported yet, don't evaluate this bit!
3	SubstDev Substitute Device detection		0	Not supported yet, don't evaluate this bit!
			1	Not supported yet, don't evaluate this bit!
4	PortActive	Port operation	0	port deactivated via port function
			1	port activated (default)
5	DevCom	Device communication	0	no IOL-Device available
			1	IOL-Device detected and is in PREOPERATE or OPERATE state
6	DevErr	Port/Device error	0	no error/warning occured
	indication		1	error/warning assigned to IOL-Device or IOL-Master port occured
7	PQ	PQ Device Process Data validity		invalid IO process data from IOL-Device
			1	valid IO process data from device

Table 34: PQI description

OUTPUT	Output	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0		
Slot 1.2	X1 Byte 1 – 32			IO-Link Port is in "Digital-Out" Mode, the "DO-C/Q" nel A, Pin 4) will be set in Bit 0 of Byte 1.							
Slot 1.3	X2 Byte 1 – 32	sta	te (Chan	nel A, Pir	14) WIII D	e set in E	Bit 0 of By	yte 1.			
Slot 1.4	X3 Byte 1 – 32										
Slot 1.5	X4 Byte 1 – 32										
Slot 1.6	X5 Byte 1 – 32										
Slot 1.7	X6 Byte 1 – 32										
Slot 1.8	X7 Byte 1 – 32										
Slot 1.9	X8 Byte 1 – 32										

Table 35: Output data: Sub-slots 1.2 - 1.9

Ch. A configuration as Digital Output

If the Port is configured as digital output, the port data length is one byte (one byte with digital output control in bit 0).

If the General device parameter Digital Out Ch. A Controlled by is set to Status/Control Module, the output cannot be controlled by bit 0 in the port output byte.

10 Diagnostics

10.1 Detailed diagnostics description

10.1.1 Error of the system/sensor power supply U_S

The voltage value for the incoming system/sensor power supply is monitored globally for the IO-Link Master. If the voltage drops below approx. 19 V, or exceeds approx. 30 V, an error message is generated. The IO-Link specification requires at least 20 V at the L+ (pin1) output supply of the I/O ports. At least 21 V of U_S supply voltage for the IO-Link Master are required to minimize the risk of internal voltage drops in the IO-Link Master.



Caution: It must definitely be ensured that the supply voltage, measured at the most remote participant is not below 21 V DC from the perspective of the system power supply.

The following IO-Link Master diagnostic is generated:

Channel number of diagnostic	0x8000 (diagnostic not channel-specific)
Channel related diagnostic code	0x0002
Channel related diagnostic code message	Undervoltage

- For disabled U_S supply voltage fault alarms, the U_S indicator LED is "off" in case of voltage drops below approx. 19 V.
- ► For **enabled** U_S supply voltage fault alarms, the U_S indicator LED is "red" in case of voltage drops below approx. 19 V.

10.1.2 Error of the actuator power supply U_L

For the following device variant, the digital outputs are supplied by U_L power:

0980 XSL 3912-121-007D-00F

The voltage value for the incoming U_L power supply is monitored globally for the IO-Link Master. If U_L supply voltage alarms are enabled, an error message is generated in case the voltage drops below approx. 19 V or exceeds approx. 30 V.

If output channels are active, additional error messages caused by the voltage failure are generated on the I/O ports. U_L supply voltage alarms are disabled by default and can be enabled via parameterization.

The following IO-Link Master diagnostic is generated:

Channel number of diagnostic	0x8000 (diagnostic not channel-specific)
Channel related diagnostic code	0x0118
Channel related diagnostic code message	Low voltage or over voltage of actuator power supply $(\mathbf{U}_{\mathrm{L}})$
Extended description	Check wire connection and ${\tt U_L}$ power supply inclusive tolerance

- For disabled U_L supply voltage fault alarms, the U_L indicator LED is "off" in case of voltage drops below approx. 19 V.
- ► For **enabled** U_L supply voltage fault alarms, the U_L indicator LED is "red" in case of voltage drops below approx. 19 V.

10.1.3 Overload/short-circuit of the I/O port sensor supply outputs

In case of an overload or a short circuit between pin 1 (L+) and pin 3 (GND) on the ports (X1 - X8), the following channel-specific diagnostic messages are generated:

Channel number of diagnostics	0x01 - 0x08
Channel related diagnostic code	0x1806
Channel related diagnostic code message	Short circuit at L+
Extended description	Short circuit on sensor power supply at pin 1 (L+) of I/O port. Check wire connection.

▶ The dedicated red port DIA indicator is active when an error is detected.

10.1.4 Overload/short circuit of the I/O port Ch. A actuator outputs

The digital outputs on the Channel A (C/Q / pin 4) are protected against short circuits and overloads. In case of a fault, the output is automatically switched to "inactive" and then cyclically switched back to "active" when the default setting is used (DO Restart Mode Parameter = "Automatic Restart after Failure").

In DO Restart Mode Parameter = "Restart after Output Reset", the output must be set to "low" via PLC, before the output can be set again to "high".

When an output channel is activated (rising edge of the channel state), the channel errors are filtered for the period that you set using the "Surveillance-Timeout" parameter during the configuration of the device. The value of this parameter can range from 0 to 255 ms; the factory setting is 80 ms.

The filter is used to avoid premature error messages when a capacitive load is activated.

The device sends the following PROFINET diagnostic message in the case of a fault:

Channel number of diagnostics	0x01 - 0x08
Channel related diagnostic code	0x1811
Channel related diagnostic code message	Short circuit at C/Q
Extended description	Short circuit or overload on digital output at pin 4 / Ch.A of IOL port in DIO mode. Check wire connection and also power supply

▶ The dedicated red port DIA indicator is active when an error is detected.



Attention: For the following device variant, the digital outputs are **supplied by the U_L power**:

▶ 0980 XSL 3912-121-007D-00F



Attention: For the following device variants, the digital outputs are supplied by the U_S power:

- ▶ 0980 LSL 3010-121-0006-001
- ▶ 0980 LSL 3011-121-0006-001

10.1.5 Overload/short circuit of the I/O port Ch. B actuator outputs

Digital outputs on Channel B (I/Q / pin 2) are only applicable for the following device variant:

▶ 0980 XSL 3912-121-007D-00F

The digital outputs on the Channel B (I/Q / pin 2) are protected against short circuits and overloads. In case of a fault, the output is automatically switched to "inactive" and then cyclically switched back to "active" when the default setting is used (DO Restart Mode Parameter = "Automatic Restart after Failure").

In DO Restart Mode Parameter = "Restart after Output Reset", the output must be set to "inactive" via PLC, before the output can be set again to "active".

When an output channel is activated (rising edge of the channel state), the channel errors are filtered for the period that you set using the "Surveillance-Timeout" parameter during the configuration of the device. The value of this parameter can range from 0 to 255 ms; the factory setting is 80 ms.

The filter is used to avoid premature error messages when a capacitive load is activated.

The device sends the following PROFINET diagnostic message in the case of a fault:

Channel number of diagnostics	0x01 - 0x08
Channel related diagnostic code	0x1810
Channel related diagnostic code message	Short circuit at I/Q
Extended description	Short circuit on digital output at pin 2 / Ch.B of I/O port in DO mode. Check wire connection and also power supply

▶ The dedicated red port DIA indicator is active when an error is detected.

10.1.6 IO-Link C/Q error

If an IO-Link Device in COM mode is unplugged, an incorrect IO-Link Device is plugged in, or an electrical fault occurs (for example due to a short circuit), an error message is generated.

If parameter Pull Plug Alarms is "enabled" (default):

A pull sub-module alarm will be send to the PROFINET controller. A message text like the following will be visible in the controller diagnostic buffer: "Hardware component removed or missing".

- ► The dedicated green port IO-Link indicator is blinking when a device is missing.
- ▶ The dedicated red port DIA indicator is off when a device is missing.

<u>If parameter **Pull Plug Alarms**</u> is "disabled" & parameter **Port Diagnostics** is "enabled":

The following diagnostic alarm will be sent to the PROFINET controller:

Channel number of diagnostics	0x01 - 0x08
Channel related diagnostic code	0x1800
Channel related diagnostic code message	No Device/communication lost

- ► The dedicated green port IO-Link indicator is blinking when a device is missing.
- ▶ The dedicated red port DIA indicator is off when a device is missing.

10.1.7 Generic parameter error

When an IO-Link Master parameter will be written to an invalid address (e.g. Sub-Slot / Index) or the parameter data content is detected as invalid for the IO-Link Master, the following IO-Link Master specific diagnostic messages will be generated:

Channel number of diagnostics	0x8000 (diagnostics not channel-specific)
Channel related diagnostic code	0x0010
Channel related diagnostic code message	Parameter error

10.1.8 I/O mapping parameter error

The individual I/O data mapping parameter of the Status/Control data will be checked by the IO-Link Master. When an error is detected inside this parameter block (e.g. a bit is mapped twice), the following message will be generated:

Channel number of diagnostics	0x8000 (diagnostics not channel-specific)
Channel related diagnostic code	0x011A
Channel related diagnostic code message	I/O mapping configuration faulty

10.1.9 Process data mismatch error

The IO-Link Master checks the configured IO-Link Sub-module data length with the detected IO-Link Device data length. In dependency of the parameter "Input Fraction", the IO-Link Master generates the following diagnostic message in case of an error:

Channel number of diagnostics	0x8000 (diagnostics not channel-specific)
Channel related diagnostic code	0x17FF
Channel related diagnostic code message	Process Data mismatch

10.1.10 Force mode diagnostic

Forcing of the I/O data is possible via the Web interface for the following device variant:

▶ 0980 XSL 3912-121-007D-00F

In case of activated forcing, the following diagnostic message will be generated:

Channel number of diagnostics	0x8000 (diagnostics not channel-specific)
Channel related diagnostic code	0x000A
Channel related diagnostic code message	Simulation active

10.1.11 Internal module error

Internal module error states (e.g. internal abnormal states) will be reported by the following diagnostic message:

Channel number of diagnostics	0x8000 (diagnostics not channel-specific)
Channel related diagnostic code	0x0009
Channel related diagnostic code message	Error

10.2 Table of IO-Link Master diagnostic codes

The following table gives an overview of the defined diagnostic codes in PROFINET (0x0000 - 0x17FF) and IO-Link (0x1800 - 0xFFFF) specification. Not all listed codes are used.

Diagnostic code	Definition	Туре
0x0000	Reserved	
0x0002	Undervoltage	Error
0x0009	Error	Error
0x000A	Simulation active	Error
0x0010	Parameter error	Error
0x0118	Low voltage of actuator power supply (UL). Check power supply	Error
0x011A	I/O mapping configuration faulty	Error
0x17FF	Process Data mismatch – check submodule configuration	Error
0x1800	No Device	Error
0x1801	Startup parametrization error - check parameter	Error
0x1802	Incorrect VendorID - Inspection Level mismatch	Error
0x1803	Incorrect DeviceID – Inspection Level mismatch	Error
0x1804	Short circuit at C/Q – check wire connection	Error
0x1805	PHY over temperature – Check master temperature and load	Error
0x1806	Short circuit at L+ - check wire connection	Error
0x1807	Overcurrent at L+ - check power supply (e.g. L1+)	Error
0x1808	Device Event overflow	Error
0x1809	Backup inconsistency - memory out of range	Error
0x180A	Backup inconsistency – identity fault	Error
0x180B	Backup inconsistency – parameter storage unspecific error	Error
0x180C	Backup inconsistency – upload fault	Error
0x180D	Parameter inconsistency – download fault	Error

Diagnostic code	Definition	Туре
0x180E	P24 (Class B) missing or undervoltage	Error
0x180F	Short circuit at P24 (Class B) – check wire connection (e.g. L2+)	Error
0x1810	Short circuit at I/Q – check wiring	Error
0x1811	Short circuit at C/Q (if digital output) – check wiring	Error
0x1812	Overcurrent at I/Q – check load	Error
0x1813	Overcurrent at C/Q (if digital output) – check load	Error
0x1814 to 0x1EFF	Reserved	
0x1F00 to 0x1FFF	Vendor specific	
0x2000 to 0x2FFF	Safety extensions	
0x3000 to 0x3FFF	Wireless extensions	
0x4000 to 0x5FFF	Reserved	
0x6000	Invalid cycle time	Error
0x6001	Revision fault	Error
0x6002	ISDU batch failed	Error
0x6003 to 0xFF20	Reserved	Error
0xFF21	Reserved	Notification
0xFF22	Reserved	Notification
0xFF23	Reserved	Notification
0xFF23	Reserved	Notification
0xFF24	Reserved	Notification
0xFF25	Reserved	Notification
0xFF26 ³	Port status changed	Notification
0xFF27 ²	Data Storage upload completed and new data object available	Notification
0xFF28 to 0xFF30	Reserved	
0xFF31	Reserved	Notification
0xFF32 to 0xFFFF	Reserved	Notification

³ For IO-Link Master internal use

10.3 IO-Link Device diagnostics in PROFINET

Diagnostics (Events) of the IO-Link Device which are sent to the IO-Link Master, are reported to the PROFINET controller via a standard channel diagnostic or an extended channel diagnostic.

Standard channel diagnostic message:

Channel number of diagnostics	0x01 - 0x08
Channel related diagnostic code	Depends on IO-Link Device diagnostics
Channel related diagnostic code message	Depends on IO-Link Device diagnostics

Extended channel diagnostic message:

Channel number of diagnostics	0x01 - 0x08
Ext. channel related diagnostic code	IO-Link Device event code

For IO-Link event codes in the range of 0x8000 - 0x7FFF, the MSB bit will be set to "0" in the PROFINET extended channel diagnostic code.

Event Code

Diagnostic code reported by the IO-Link Device. Use the IO-Link Device documentation to interpret the error message.

Channel Number

1 - 8 of the IO-Link Master port whose connected device is reporting an error.

10.4 Table of IO-Link Device diagnostic codes

The following table shows the defined diagnostic codes (events) of the IO-Link specification. Use the IO-Link Device documentation for vendor specific codes.

Diagnostic code	Definition	Туре
0x0000	No malfunction	Notifcation
0x1000	General malfunction – unknown error	Error
0x1001 to 0x17FF	Reserved	
0x1800 to 0x18FF	Vendor specific	
0x1900 to 0x3FF	Reserved	
0x4000	Temperature fault – Overload	Error
0x4001 to 0x420F	Reserved	
0x4210	Device temperature overrun – Clear source of heat	Warning
0x4211 to 0x421F	Reserved	
0x4220	Device temperature underrun – Insulate Device	Warning
0x4221 to 0x4FFF	Reserved	
0x5000	Device hardware fault – Device exchange	Error
0x5001 to 0x500F	Reserved	
0x5010	Component malfunction – Repair or exchange	Error
0x5011	Non volatile memory loss – Check batteries	Error
0x5012	Batteries low – Exchange batteries	Warning
0x5013 to 0x50FF	Reserved	
0x5100	General power supply fault – Check availability	Error
0x5101	Fuse blown/open – Exchange fuse	Error
0x5102 to 0x510F	Reserved	
0x5013 to 0x50FF	Reserved	

Diagnostic code	Definition	Туре
0x5100	General power supply fault – Check availability	Error
0x5101	Fuse blown/open – Exchange fuse	Error
0x5102 to 0x510F	Reserved	
0x5110	Primary supply voltage overrun – Check tolerance	Warning
0x5111	Primary supply voltage underrun – Check tolerance	Warning
0x5112	Secondary supply voltage fault (Port Class B) – Check tolerance	Warning
0x5113 to 0x5FFF	Reserved	
0x6000		
0x6001 to 0x631F	Reserved	
0x6320	Parameter error – Check data sheet and values	Error
0x6321	Parameter missing – Check data sheet	Error
0x6322 to 0x634F	Reserved	
0x6350	Reserved	
0x6351 to 0x76FF	Reserved	
0x7700	Wire break of a subordinate device – Check installation	Error
0x7701 to 0x770F	Wire break of subordinate device 1device 15 – Check installation	Error
0x7710	Short circuit – Check installation	Error
0x7711	Ground fault – Check installation	Error
0x7712 to 0x8BFF	Reserved	
0x8C00	Technology specific application fault – Reset Device	Error
0x8C01	Simulation active – Check operational mode	Warning
0x8C02 to 0x8C0F	Reserved	
0x8C10	Process variable range overrun – Process Data uncertain	Warning
0x8C11 to 0x8C1F	Reserved	
0x8C20	Measurement range exceeded – Check application	Error
0x8C21 to 0x8C2F	Reserved	
0x8C30	Process variable range underrun – Process Data uncertain	
0x8C31 to 0x8C3F	Reserved	

Diagnostic code	Definition	Туре
0x8C40	Maintenance required – Cleaning	Warning
0x8C41	Maintenance required – Refill	Warning
0x8C42	Maintenance required – Exchange wear and tear parts	Warning
0x8C43 to 0x8C9F	Reserved	
0x8CA0 to 0x8DFF	Vendor specific	
0x8E00 to 0xAFFF	Reserved	
0xB000 to 0xB0FF	Reserved for Safety extensions	
0xB100 to 0xBFFF	Reserved for Profiles	
0xC000 to 0xFF90	Reserved	
0xFF91	Internal	Notification
0xFF92 to 0xFFAF	Reserved	
0xFFB0 to 0xFFB7	Reserved for Wireless extensions	
0xFFB8 to 0xFFFF	Reserved	

11 IIoT functionality

The Lion-X variants offer a number of new interfaces and functions for the optimal integration into existing or future IIoT (Industrial Internet of Things) networks. The devices continue to work as field bus devices which communicate with and are controlled by a PLC (Programmable Logic Controller).

In addition, the devices offer common IIoT interfaces, which enable new communication channels besides the PLC. The communication is performed via IIoT-relevant protocols MQTT and OPC UA. With the help of these interfaces not only all information in a LioN-X device can be read. They also enable its configuration and control, if the user wishes. All interfaces can be configured extensively and offer read-only functionality.

All LioN-X variants provide user administration, which is also applicable for accessing and configuring the IIoT protocols. This allows you to manage all modification options for the device settings via personalized user authorizations.

All IIoT protocols can be used and configured independently of the field bus. It is also possible to use the devices completely without the help of a PLC and control them via IIoT protocols.



Attention: When using the IIoT functionality, a protected local network environment without direct access to the Internet is recommended.

11.1 MQTT

MQTT functions are **only** applicable for the following LioN-X variant:

▶ 0980 XSL 3912-121-007D-00F

The MQTT (Message Queuing Telemetry Transport) protocol is an open network protocol for machine-to-machine communication, which provides the transmission of telemetric data messages between devices. The integrated MQTT client allows the device to publish a specific set of information to an MQTT broker.

The publishing of messages can either occur periodically or be triggered manually.

11.1.1 MQTT configuration

In **delivery state**, MQTT functions are **disabled**. The MQTT client can be configured either using the Web interface or directly via a JSON object sent in an HTTP request. For more information see chapter MQTT configuration - Quick start guide on page 146.

The configuration URL is:

http://[ip-address]/w/config/mqtt.json

The configuration can also read back as a JSON file:

http://[ip-address]/r/config/mqtt.json

The configuration is a JSON object. Each JSON member is a configuration element. The object must not contain all elements. Only the provided elements will be changed. The configuration changes apply only after a device restart

The following configuration elements are available (default values in bold):

Element	Data type	Description	Example data	
mqtt-enable	boolean	Master switch for the MQTT client.	true / false	
broker	string	IP address of the MQTT Broker	"192.168.1.1"	
login	string	Username for MQTT Broker	"admin" (Default: null)	
password	string	Password for MQTT Broker	"private" (Default: null)	
port	number	Broker port	1883	
base-topic	string	Base topic	"iomodule_[mac]" (Default: " lionx ")	
will-enable	boolean	If true, the device provides a last will message to the broker	true / false	
will-topic	string	The topic for the last will message.	(Default: null)	
auto-publish	boolean	If true, all enabled domains will be published automatically in the specified interval.	true / false	
publish-interval	number	The publish interval in ms if autopublish is enabled. Minimum is 250 ms.	2000	
publish-identity	boolean	If true, all identity domain data will be published	true / false	
publish-config	boolean	If true, all config domain data will be published	true / false	
publish-status	boolean	If true, all status domain data will be published	true / false	
publish-process	boolean	If true, all process domain data will be published	true / false	
publish-devices	boolean	If true, all IO-Link Device domain data will be published	true / false	
commands-allowed	boolean	Master switch for MQTT commands. If false, the device will not subscribe to any command topic, even if specific command topics are activated below.	true / false	
force-allowed	boolean	If true, the device accepts force commands via MQTT.	true / false	
reset-allowed	boolean	If true, the device accepts restart and factory reset commands via MQTT.	true / false	
config-allowed	boolean	If true, the device accepts configuration changes via MQTT.	true / false	

Element	Data type	Description	Example data
qos	number	for all published messages.	0 = At most once 1 = At least once 2 = Exactly once

Table 36: MQTT configuration

MQTT response:

The resulting response is a JSON object with a "status" field. Status should be "0" if no error occurred and "-1" if there is an error.

In case of an error, the response contains an error array.

The error array contains an error object for each error occurred. The object consists of a field "Element" which names the config element which caused the error, and a field "Message" for the error message.

- A malformed JSON object produces an error.
- Not existing parameters produce an error.
- Parameters with a wrong data type produce an error.

It is not allowed to write all available parameters at once. You may write only one or a limited number of parameters.

Examples:

```
{"status": -1, "error": [{"Element": "publish-interval", "Message": "Integer
expected"}]}
{"status": 0}
{"status": -1, "error": [{"Element": "root", "Message": "Not a JSON
object"}]}
```

For more information see chapter MQTT topics on page 138.

11.1.2 MQTT topics

MQTT mainly relates to topics. All messages are attached to a topic which adds context to the message itself. Topics may consist of any string and they are allowed to contain slashes (/) as well as wildcard symbols (*, #).

11.1.2.1 Base topic

For LioN-X and the LioN-Xlight variants there is a configurable *Base topic* which is the prefix for all topics. The *Base topic* can be chosen freely by the user. The *Base topic* can also contain selected variables as shown in Table 37: Base topic variables on page 138.

Variables in the *Base topic* have to be written in brackets ("[]"). The following variables are possible:

Variable Description		
mac	The MAC address of the device	
name	The name of the device	
order	The ordering number of the device	
serial	The serial number of the device	

Table 37: Base topic variables

Example:

The Base topic "io_[mac]" translates to "io_A3B6F3F0F2F1".

All data is organized in domains. The domain name is the first level in the topic after the *Base topic*. Note the following notation:

Base-Topic/domain/.....

There are the following domains:

Domain name	Definition	Example content
identity	All fixed data which is defined by the used hardware and which cannot be changed by configuration or at runtime.	Device name, ordering number, MAC address, port types, port capabilites and more.
config	Configuration data which is commonly loaded once at startup, mostly by a PLC.	IP address, port modes, input logic, failsafe values and more.
status	All (non-process) data which changes quite often in normal operation.	Bus state, diagnostic information, IO- Link device status and data.
process	All process data which is produced and consumed by the device itself or by attached devices.	Digital inputs, digital outputs, cyclic IO- Link data.
iold	IO-Link device parameters according to the IO-Link specification.	Vendor name, product name, serial number, hardware revision, software revision and more.

Table 38: Data domains

There is often one topic used for all gateway related information and topics for each port. All identity topics are published just once at start-up, because this information should never change. All other topics are published either in a fixed interval or just triggered manually, according to the configuration.

Topic	Content examples	Total publish count	Publish interval
[base-topic]/identity/ gateway	Name, ordering number, MAC, vendor, I&M etc.	1	Startup
[base-topic]/identity/ port/n	Port name, port type	8	Startup
[base-topic]/config/ gateway	Configuration parameters, ip address etc.	1	Interval
[base-topic]/config/port/ n	Port mode, data storage, mapping, direction	8	Interval
[base-topic]/status/ gateway	Bus state, device diagnosis, master events	1	Interval
[base-topic]/status/port/ n	Port or channel diagnosis, IO-Link state, IO- Link device events	8	Interval
[base-topic]/process/ gateway	All Digital IN/OUT	1	Interval
[base-topic]/process/ port/n	Digital IN/OUT per port, IOL-data, pdValid	8	Interval
[base-topic]/iold/port/n	IO-Link device parameter	8	Interval

Table 39: Data model

An MQTT client which wants to subscribe to one or more of these topics can also use wildcards.

Full topic	Description		
[base-topic]/identity/gateway	Receive only indentity objects for the gateway		
[base-topic]/identity/#	Receive all data related to the identity domain		
[base-topic]/status/port/5	Receive only status information for port number 5		
[base-topic]/+/port/2	Receive information of all domains for port number 2		
[base-topic]/process/port/#	Receive only process data for all ports		
[base-topic]/config/#	Receive config data for the gateway and all ports.		

Table 40: Topic use case examples

11.1.2.2 Publish topic

Overview of all publish JSON data for the defined topics:

Key	Data type
tbd	json_string
ordering_number	json_string
device_type	json_string
serial_number	json_string
mac_address	json_string
production_date	json_string
fw_name	json_string
fw_date	json_string
fw_version	json_string
hw_version	json_string
vendor_name	json_string
vendor_address	json_string
vendor_phone	json_string
vendor_email	json_string
vendor_techn_support	json_string
vendor_url	json_string
vendor_id	json_integer
device_id	json_integer

Table 41: Identity/gateway

Key	Data type	Range	Default value	Remarks
fieldbus_protocol	json_string	profinet, ethernet/ip, ethercat		
network_configuration	json_string	PNS: dcp EIS: stored_value, bootp, dhcp		
rotary_switches	json_integer	0999		
ip_address	json_string		192.168.1.1	
subnet_mask	json_string		255.255.255.0	
report_alarms	json_boolean		0.0.0.0	
report_ul_alarm	json_boolean	true / false	true	
report_do_fault_without_ul	json_boolean	true / false	false	
force_mode_lock	json_boolean	true / false	false	
web_interface_lock	json_boolean	true / false	false	
do_auto_restart	json_boolean	true / false	true	
fast_startup	json_boolean	true / false	false	PROFINET and EIP only

Table 42: Config/gateway

Key	Data type	Range	Default value	Remarks
protocol	json_string	wait_for_io_system wait_for_io_Connection failsafe connected error		
ethernet_port1	json_string	100_mbit/s_full 100_mbit/s 10_mbit/s_full 100_mbit/s		
ethernet_port2	json_string	100_mbit/s_full 100_mbit/s 10_mbit/s_full 100_mbit/s		
module_restarts	json_integer	04294967295		
channel_diagnosis	json_boolean	true / false		
failsafe_active	json_boolean	true / false		
system_voltage_fault	json_boolean	true / false		
actuator_voltage_fault	json_boolean	true / false		
internal_module_error	json_boolean	true / false		
forcemode_enabled	json_boolean	true / false		

Table 43: Status/gateway

Key	Data type	Range	Default value	Remarks
Input_data	json_integer[]			
output_data	json_integer[]			

Table 44: Process/gateway

Key	Data type	Range	Default value	Remarks
port	json_integer	18		
type	json_string	digital_universal digital_input digital_Output io_link		
max_output_power_cha	json_string	2.0_mA 0.5_mA		
max_output_power_chb	json_string	2.0_mA 0.5_mA		
channel_cha	json_string	input/output input output io_link aux		
channel_chb	json_string	input/output input output io_link aux		

Table 45: Identity/port/1 ... 8

Key	Data type	Range	Default value	Remarks
port	json_integer	18		
direction_cha	json_string	input/output input output		
direction_chb	json_string	input/output input output		
failsafe_cha	json_string	set_low set_high hold_last	set_low	
failsafe_chb	json_string	set_low set_high hold_last	set_low	
surveillance_timeout_cha	json_integer	0255	80	
surveillance_timeout_chb	json_integer	0255	80	

Table 46: Config/port/1 ... 8

Key	Data type	Range	Default value	Remarks
port	json_integer	18		
physical_state_cha	json_integer	01		
physical_state_chb	json_integer	01		
actuator_short_circuit_cha	json_boolean	true / false		
actuator_short_circuit_chb	json_boolean	true / false		
sensor_short_circuit	json_boolean	true / false		

Table 47: Status/port/1 ... 8

11.1.3 MQTT configuration - Quick start guide



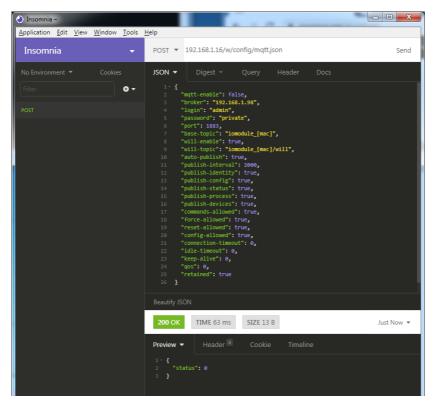
Attention: Lumberg AutomationTM is not responsible for any content of the referenced Web pages and provides no warranty for any functionality of the named third party software.

11.1.3.1 MQTT configuration via JSON

1. Depending on your application case, download and install *Insomnia* or a comparable application: https://insomnia.rest/download/

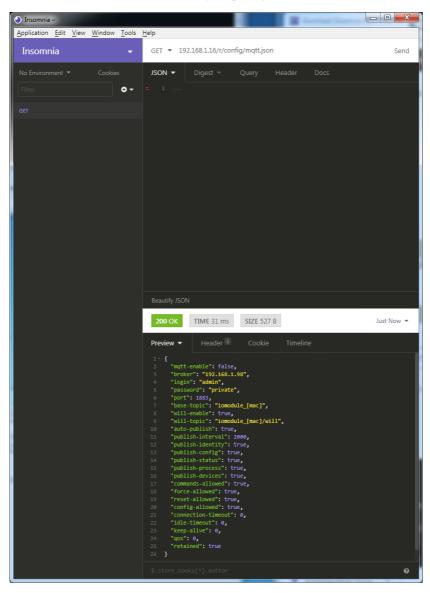
2. Configure MQTT:

POST: [IP-address]/w/config/mqtt.json



3. Read MQTT:

GET: [IP-address]/r/config/mqtt.json



11.2 OPC UA

OPC UA functions are **only** applicable for the following LioN-X variant:

0980 XSL 3912-121-007D-00F

OPC Unified Architecture (OPC UA) is a platform-independent standard with a service-oriented architecture for communication in and with industrial automation systems.

The OPC UA standard is based on the client-server principle and lets machines and devices, regardless of any preferred field bus, communicate horizontally among each other as well as vertically to the ERP system or the cloud. LioN-X provides an OPC UA server on field device level, with which an OPC UA client can connect for information exchange secure in transmission.

For OPC UA, we comply (apart from the exceptions listed below) with the IO-Link Companion Specification, which can be downloaded from catalog.belden.com or directly from io-link.com.

Feature	Support
Managing IODDs (chapter 6.1.6 in the specification)	Not supported
Mapping IODD information to OPC UA ObjectTypes (chapter 6.3 in the specification)	Not supported
IOLinkIODDDeviceType (chapters 7.2 ff. in the specification)	Not supported
ObjectTypes generated based on IODDs (chapters 7.3 ff. in the specification)	Not supported
Creation of Instances based on ObjectTypes generated out of IODDs (chapter 7.4 in the specification)	Not supported
IODDManagement Object (chapter 8.2 in the specification)	Not supported
RemovelODD Method (chapter 8.3 in the specification)	Not supported

Table 48: Non-supported OPC UA features according to the IO-Link Companion Specification

11.2.1 OPC UA configuration

In **delivery state**, OPC UA functions are **disabled**. The OPC UA Server can be configured either using the Web interface or directly via a JSON Object sent in an HTTP request. For more information see OPC UA configuration - Quick start guide on page 152.

The configuration URL is:

http://[ip-address]/w/config/opcua.json

The configuration can also read back as a JSON file:

http://[ip-address]/r/config/opcua.json

The configuration is a JSON object. Each JSON member is a configuration element. The object must not contain all elements. Only the provided elements will be changed. All configuration changed applies only after a device restart.

There are the following configuration elements (default values in bold):

Element	Data type	Description	Example data
port	integer	Server port for the OPC UA server.	0, 4840 , 0xFFFF
opcua-enable	boolean	Master switch for the OPC UA server.	true / false
anon-allowed	boolean	If true, anonymous login is allowed.	true / false
commands-allowed	boolean	Master switch for OPC UA commands. If false there will be no writeable OPC UA objects.	true / false
force-allowed	boolean	If true, the device accepts force commands via OPC UA.	true / false
reset-allowed	boolean	If true, the device accepts restart and factory reset commands via OPC UA.	true / false
config-allowed	boolean	If true, the device accepts configuration changes via OPC UA.	true / false

Table 49: OPC UA Configration

All configuration elements are optional and do not need a specific order. Not every element is required to be sent. This means that only configuration changes will be taken over.

Optional: The configuration parameters of OPC UA can be set directly via the Web interface. It is possible to download the Web interface for sharing with other devices.

Response:

The resulting response is a JSON object with a "status" field. Status should be 0 if no error occurred and -1 if there is an error.

In case of an error, the response contains an error array.

The error array contains an error object for each error occurred. The object consists of a field "Element" which names the config element which caused the error, and a field "Message" for the error message.

Examples:

```
{"status": -1, "error": [{"Element": "upcua-enable", "Message": "Boolean
expected"}]}

{"status": 0}

{"status": -1, "error": [{"Element": "root", "Message": "Not a JSON
object"}]}
```

11.2.2 OPC UA address space

OPC UA provides different services on the LioN-X devices with which a client can navigate through the hierarchy of the address space and read or write variables. In addition, the client can monitor up to 10 attributes from the address space for value changes.

A connection to an OPC UA server is established via the endpoint URL:

```
opc.tcp://[ip-address]:[port]
```

Various device data such as MAC address, device settings, diagnostics or status information can be read via *Identity objects*, *Config objects*, *Status objects* and *Process objects*.

Command objects can be read and written. This makes it possible, for example, to transfer new network parameters to the device, to use Force Mode or to reset the entire device to its factory settings.

The following figures illustrate the OPC UA address space of the LioN-X devices. The objects and information displayed depend on the device variant used.

11.2.3 OPC UA configuration - Quick start guide



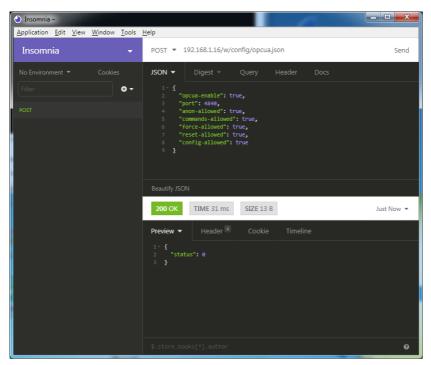
Attention: Lumberg AutomationTM is not responsible for any content of the referenced Web pages and provides no warranty for any functionality of the named third party software.

11.2.3.1 OPC UA configuration via JSON

1. Depending on your application case, download and install *Insomnia* or a comparable application: https://insomnia.rest/download/

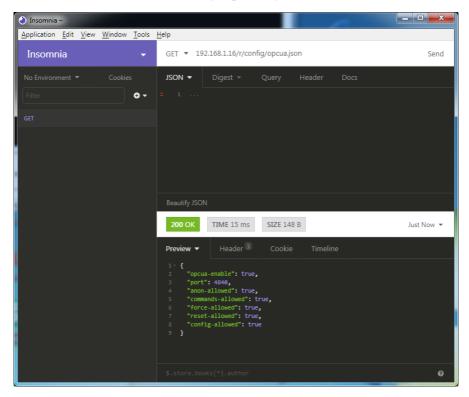
2. Configure OPC UA:

POST: [IP-address]/w/config/opcua.json



3. Read OPC UA:

GET: [IP-address]/r/config/opcua.json



11.3 REST API

The Representational State Transfer – Application Programming Interface (REST API) is a programmable interface which uses HTTP requests to GET and POST data. This enables the access to detailed device information.

For LioN-X and the LioN-Xlight variants, the REST API can be used to read the device status. For the LioN-X multiprotocol variants, the REST API can also be used to write configuration and forcing data.

There are two different REST API standards you can use for the requests:

1. A standardized REST API that has been specified by the IO-Link Community and is described separately:

```
JSON_Integration_10222_V100_Mar20.pdf
```

Please download the file from catalog.belden.com or directly from iolink.com.



Attention: Consider the following table to get an overview of the supported features of the IO-Link specification:

Feature		Supported
Gateway	GET /identification	Yes
	GET /capabilities	Yes
	GET /configuration	Yes
	POST /configuration	Yes
	POST /reset	Yes
	POST /reboot	Yes
	GET /events	Yes
Master	GET /masters	Yes
	GET /capabilities	Yes
	GET /identification	Yes
	POST /identification	Yes

Feature		Supported
Port	GET /ports	Yes
	GET /capabilities	Yes
	GET /status	Yes
	GET /configuration	Yes
	POST /configuration	Yes
	GET /datastorage	Not supported
	POST /datastorage	Not supported
Devices	GET /devices	Yes
	GET /capabilities	Yes
	GET /identification	Yes
	POST /identification	Yes
	GET /processdata/value	Yes
	GET /processdata/getdata/value	Yes
	GET /processdata/setdata/value	Yes
	POST /processdata/value	Yes
	GET /parameters	Yes
	GET /parameters/{index}/subindices	Yes
	GET /parameters/{parameterName}/subindices	Not supported
	GET /parameters/{index}/value	Yes
	GET /parameters/{index}/subindices/{subindex}/value	Yes
	GET /parameters/{parameterName}/value	Not supported
	GET /parameters/{parameterName}/subindices/ {subParameterName}/value	Not supported
	POST /parameters/{index}/value	Yes
	POST /parameters/{parameterName}/value	Not supported
	POST /parameters/{index}/subindices/{subindex}/value	Yes
	POST /parameters/{parameterName}/subindices/ {subParameterName}/value	Not supported
	POST /blockparametrization	Not supported
	GET /events	Yes

Feature		Supported
IODD	GET /iodds	Not supported
	POST /iodds/file	Not supported
	DELETE /iodds	Not supported
	GET /iodds/file	Not supported

Table 50: Support of REST API features according to the IO-Link specification

2. A customized Belden REST API that is described in the following chapters.

11.3.1 Standard device information

Request method: http GET

Request URL: <ip>/info.json

Parameters n.a.

Response format JSON

The goal of the "Standard device information" request is to get a complete snapshot of the current device status. The format is JSON. For IO-Link devices, all ports with connected IO-Link device information are included.

11.3.2 Structure

Name	Data type	Description	Example
name	string	Device name	"0980 XSL 3912- 121-007D-00F"
order-id	string	Ordering number	"935 700 001"
fw-version	string	Firmware version	"V.1.1.0.0 - 01.01.2021"
hw-version	string	Hardware version	"V.1.00"
mac	string	MAC address of the device	"3C B9 A6 F3 F6 05"
bus	number	0 = No connection 1 = Connection with PLC	1
failsafe	number	0 = Normal operation 1 = Outputs are in failsafe	0
ip	string	IP address of the device	
snMask	string	Subnet Mask	
gw	string	Default gateway	
rotarys	array of numbers (3)	Current position of the rotary switches: Array element 0 = x1 Array element 1 = x10 Array element 2 = x100	
ulPresent	boolean	True, if there is a UL voltage supply detected within valid range	
usVoltage_mv	number	US voltage supply in mV	
ulVoltage_mv	number	UL voltage supply in mV (only available for devices with UL supply)	
inputs	array of numbers (2)	Real state of digital inputs. Element 0 = 1 Byte: Port X1 Channel A to Port X4 Channel B Element 0 = 1 Byte: Port X5 Channel A to Port X8 Channel B	\[128,3\]
output	array of numbers (2)	Real State of digital outputs. Element 0 =1 Byte: Port X1 Channel A to port X4 Channel B Element 0 = 1 Byte: Port X5 Channel A to port X8 Channel B	\[55,8\]

Name	Data type	Description	n	Example
consuming	array of numbers (2)	Cyclic data	from PLC to device	
producing	array of numbers (2)	Cyclic data	from device to PLC	
diag	array of numbers (4)	Diagnostic information		
fieldbus	FIELDBUS Object			
FIELDBUS Object				
fieldbus_name	string	Currently us	sed fieldbus	
state	number	Fieldbus sta	ate	
state_text	number	Textual representation of fieldbus state: 0 = Unknown 1 = Bus disconnected 2 = Preop 3 = Connected 4 = Error 5 = Stateless		
forcing	FORCING Object	Information the device	about the forcing state of	

Name	Data type	Description	Example
channels	Array of CHANNEL (16)	Basic information about all input/output channels	
iol	IOL Object	Contains all IO-Link related information such as events, port states, device parameters.	
iol/diagGateway	array of DIAG	Array of currently active device/ gateway related events	
iol/diagMaster	array of DIAG	Array of currently active IOL-Master related events	
iol/ports	array of PORT (8)	Contains one element for each IO-Link port	
CHANNEL Object			
name	string	Name of channel	
type	number	Hardware channel type as number: 0 = DIO 1 = Input 2 = Output 3 = Input/Output 4 = IO-Link 5 = IOL AUX 6 = IOL AUX with DO 7 = IOL AUX with DO. Can be deactivated. 8 = Channel not available	
type_text	string	Textual representation of the channel type	
config	number	Current configuration of the channel: 0 = DIO 1 = Input 2 = Output 3 = IO-Link 4 = Deactivated 5 = IOL AUX	
config_text	string	Textual representation of the current config	
inputState	boolean	Input data (producing data) bit to the PLC	

Name	Data type	Description	Example
outputState	boolean	Output data bit to the physical output pin	
forced	boolean	True, if the output pin of this channel is forced	
simulated	boolean	True, if the input value to the PLC of this channel is simulated	
actuatorDiag	boolean	True, if the output is in short circuit / overload condition	
sensorDiag	boolean	True, if the sensor supply (Pin 1) is in short circuit / overload condition	
maxOutputCurrent _mA	number	Maximum output current of the output in mA	
current_mA	number	Measured current of the output in mA (if current measurement is available)	
voltage_mV	number	Measured voltage of this output in mV (if voltage measurement is available)	
PORT Object			
port_type	string	Textual representation of the IO-Link port type	
iolink_mode	number	Current port mode: 0 = Inactive 1 = Digital output 2= Digital input 3 = SIO 4 = IO-Link	
iolink_text	string	Textual representation of the current port mode	"Digital Input"
aux_mode	number	Indicates the configured mode for the Pin 2: 0 = No AUX 1 = AUX output (always on) 2 = Digital output (can be controlled by cyclic data) 3 = Digital input	
aux_text	string	Textual representation of the current aux mode	"AUX Output"
cq_mode	number	Port mode according to IOL specification	

Name	Data type	Description	Example
iq_mode	number	Pin2 mode according to IOL specification	
port_status	number	Port status according to IOL specification	
ds_fault	number	Data storage error number	
ds_fault_text	string	Textual data storage error.	
device	DEVICE Object	IO-Link device parameters. → Null if no IO-Link communication active	
diag	array of DIAG (n)	Array of port related events	
DIAG Object			
error	number	Error code	
source	string	Source of the current error.	"device" "master"
eventcode	number	Event code according to IO-Link specification	
eventqualifier	number	Event qualifier according to IO-Link specification	
message	string	Error message	"Supply Voltage fault"
DEVICE Object		Standard parameters of the IOL-Device	
device_id	number		
vendor_id	number		
serial	string		
baudrate	string	Baudrate (COM1,2,3)	
cycle_time	number	Cycle time in microseconds	
input_len	array of numbers (n)	IOL input length in bytes	
output_len	array of numbers (n)	IOL output length in bytes	
input_data	array of numbers (n)	IOL input data	
output_data	array of numbers (n)	IOL output data	
pd_valid	number	"1", if IOL input data is valid	
pdout_valid	number	"1", if IOL output data is valid	
FORCING Object		Forcing information of the device	

Name	Data type	Description	Example
forcingActive	boolean	Force mode is currently active	
forcingPossible	boolean	True, if forcing is possible and force mode can be activated	
ownForcing	boolean	True, if forcing is performed by REST API at the moment	
forcingClient	string	Current forcing client identifier	
digitalOutForced	array of numbers (2)	The force values of all 16 digital output channels.	
digitalOutMask	array of numbers (2)	The forcing mask of all 16 digital output channels.	
digitalInForced	array of numbers (2)	The force values of all 16 digital input channels.	
digitalInMask	array of numbers (2)	The forcing mask of all 16 digital input channels.	

11.3.3 Configuration and forcing

Method: POST

URL: <ip>/w/force.json

Parameters: None

Post-Body: JSON Object

Property	Data type	Example values	Description
forcemode	boolean	true / false	Forcing authority on/off
portmode	array (Port mode object)		
digital	array (Digital object)		
iol	array (IOL object)		

Table 51: Root object

Property	Data type	Example values	Remarks
port	integer	07	
channel	integer	"a","b"	optional default is "a"
direction	string	"dio","di","do","iol", "off", "aux"	
aux	string	"dio","di","do","iol", "off", "aux"	IOL only, but optional
inlogica	string	"no","nc"	
inlogicb	string	"no","nc"	

Table 52: Port mode object

Property	Data type	Example values	Remarks
port	integer	07	
channel	string	"a","b"	
force_dir	string	"phys_out","plc_in","clear"	optional default is "phys_out"
force_value	integer	0,1	

Table 53: Digital object

Property	Data type	Example values	Remarks
port	integer	07	
output	array[integer] or null to clear forcing	[55,88,120]	Output forcing
input	array[integer] or null to clear forcing	[20,0,88]	Input simulation to PLC

Table 54: IOL object

11.3.4 Reading and writing ISDU parameters

The *Indexed Service Data Unit* (ISDU) provides a highly flexible message format, which can contain single or multiple commands.

LioN-X IOL-Masters with IIoT support reading and writing ISDU parameters from connected IOL-Devices. It is possible to do this as a bulk transfer by reading and writing of multiple ISDU parameters via a single request.

11.3.4.1 Reading ISDU

Method: POST

URL: <ip>/r/isdu.json

Parameters: port (0-7)

Example: 192.168.1.20/r/isdu.json?port=5

Post-Body: JSON array of read ISDU object

Property	Data type	Example values	Remarks
ix	integer	0-INT16	Index to be read
subix	integer	0-INT8	Subindex to be read

Table 55: Read ISDU object

Property	Data type	Example values	Remarks
status	integer	0, -1	0 = no error, -1= an error occured
message	string		Error Message if error occured
data	array (Read ISDU data object)		data, if no error occured. otherweise null

Table 56: Read ISDU response object

Property	Data type	Example values	Remarks
ix	integer	0-INT16	Index that was read
subix	integer	0-INT8	Subindex that was read
status	integer	0, -1	0 = no error, -1= an error occured
eventcode	integer		IOL eventcode if status is -1
data	array[integer]		data, if no error occured. otherweise null

Table 57: Read ISDU data object

11.3.4.2 Writing ISDU

Method: POST

URL: <ip>/w/isdu.json

Parameters: port (0-7)

Post-Body: JSON array of write ISDU object

Property	Data type	Example values	Remarks
ix	integer	0-INT16	Index to be read
subix	integer	0-INT8	Subindex to be read
data	array[integer]		Data to be written

Table 58: Write ISDU object

Response: Write ISDU response object

Property	Data type	Example values	Remarks
status	integer	0, -1	0 = no error, -1= an error occured
message	string		Error Message if error occured
data	array (Write ISDU data object)		data, if no error occured. otherweise null

Table 59: Write ISDU response object

Property	Data type	Example values	Remarks
ix	integer	0-INT16	Index that was written
subix	integer	0-INT8	Subindex that was written
status	integer	0, -1	0 = no error, -1= an error occured
eventcode	integer		IOL eventcode if status is -1

Table 60: Write ISDU data object

11.3.5 Example: Reading ISDU

ISDU read request

Response

11.3.6 Example: Writing ISDU

ISDU write request

```
[
    {"ix":24,"subix":0,"data":[97,98,99,100,101,102]},
    {"ix":9,"subix":0,"data":[97,97,97,97,98]}
]
```

Response

11.4 CoAP server

The CoAP server functions are **only** applicable for the following LioN-X variant:

0980 XSL 3912-121-007D-00F

The **Co**nstrained **A**pplication **P**rotocol (CoAP) is a specialized Internet application protocol for constrained networks such as lossy or low power networks. CoAP is useful especially in M2M (Machine to Machine) communication and can be used to translate simplified HTTP requests of low speed networks.

CoAP is based on the Server-Client principle and a service layer protocol that lets nodes and machines communicate with each other. The LioN-X multiprotocol variants provide CoAP server functionalities via a REST API interface over UDP.

11.4.1 CoAP configuration

In **delivery state**, CoAP functions are **disabled**. The CoAP server can be configured either using the Web interface or directly via a JSON object sent in an HTTP request. For more information see chapter CoAP configuration - Quick start guide on page 174.

The configuration URL is:

http://[ip-address]/w/config/coapd.json

The configuration can also read back as a JSON file:

http://[ip-address]/r/config/coapd.json

The configuration is a JSON object. Each JSON member is a configuration element. The object must not contain all elements. Only the provided elements will be changed. The configuration changes apply only after a device restart

The following configuration elements are available (default values in bold):

Element	Data type	Description	Example data
enable	boolean	Master switch for the CoAP server	true / false
port	integer (0 to 65535)	Port of the CoAP server	5683

Table 61: CoAP configuration

CoAP response:

The resulting response is a JSON object with a "status" field. Status should be "0" if no error occurred, and "-1" if there is an error.

In case of an error, the response contains an error array.

The error array contains an error object for each error occurred. The object consists of a field "Element" which names the config element that caused the error, and of a field "Message" for the error message.

Examples:

```
{"status": -1, "error": [{"Element": "upcua-enable", "Message": "Boolean
expected"}]}

{"status": 0}

{"status": -1, "error": [{"Element": "root", "Message": "Not a JSON
object"}]}
```

11.4.2 REST API access via CoAP

A connection to the CoAP server running on the LioN-X multiprotocol variants can be established via the following URL:

```
coap://[ip-address]:[port]/[api]
```

For LioN-X, the following REST API Requests (JSON format) can be accessed via a CoAP endpoint:

Туре	API	Note		
GET	/r/status.lr			
GET	/r/system.ir			
GET	/info.json"			
GET	/r/config/net.json			
GET	/r/config/mqtt.json			
GET	/r/config/opcua.json			
GET	/r/config/coapd.json			
GET	/r/config/syslog.json			
GET	/contact.json			
GET	/fwup_status			
GET	/iolink/v1/gateway/identification			
GET	/iolink/v1/gateway/capabilities			
GET	/iolink/v1/gateway/configuration			
GET	/iolink/v1/gateway/events			
GET	/iolink/v1/masters			
GET	/iolink/v1/masters/1/capabilities			
GET	/iolink/v1/masters/1/identification			
GET	/iolink/v1/masters/1/ports			
GET	/iolink/v1/masters/1/ports/{port_number}/capabilities	This API is available for all 8 ports. {port_number} should be between "1" and "8".		
GET	/iolink/v1/masters/1/ports/{port_number}/status	This API is available for all 8 ports. {port_number} should be between "1" and "8".		
GET	/iolink/v1/masters/1/ports/{port_number}/configuration	This API is available for all 8 ports. {port_number} should be between "1" and "8".		
GET	/iolink/v1/devices/master1port{port_number}/identification	This API is available for all 8 ports. {port_number} should be between "1" and "8".		

Туре	API	Note
GET	/iolink/v1/devices/master1port{port_number}/capabilities	This API is available for all 8 ports. {port_number} should be between "1" and "8".
GET	/iolink/v1/devices/master1port{port_number}/processdata/ getdata/value	This API is available for all 8 ports. {port_number} should be between "1" and "8".
GET	/iolink/v1/devices/master1port{port_number}/events	This API is available for all 8 ports. {port_number} should be between "1" and "8".

Table 62: REST API access via CoAP

11.4.3 CoAP configuration - Quick start guide



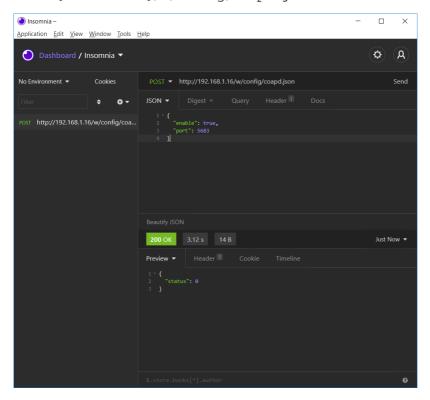
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11.4.3.1 CoAP configuration via JSON

1. Depending on your application case, download and install *Insomnia* or a comparable application: https://insomnia.rest/download/

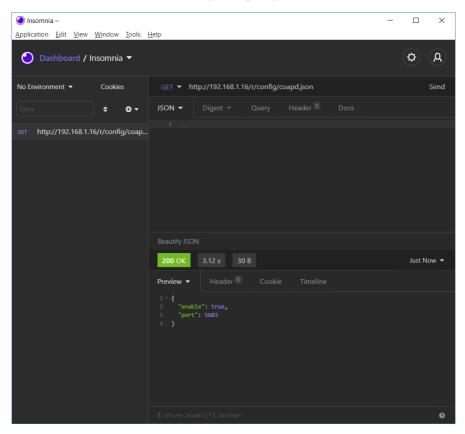
2. Configure CoAP:

POST: [IP-address]/w/config/coapd.json



3. Read CoAP configuration:

GET: [IP-address]/r/config/coapd.json



11.5 Syslog

Syslog functions are **only** applicable for the following LioN-X variant:

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The LioN-X multiprotocol variants provide a Syslog client which can connect with a configured Syslog server and is able to log messages.

Syslog is a platform-independent standard for logging messages. Each message contains a timestamp as well as information about the severity level and the subsystem. The Syslog protocol RFC5424 is based on the Server-Client principle and lets machines and devices send messages in the network and collect them centrally. (For more details on the used syslog standard, please refer to https://datatracker.ietf.org/doc/html/rfc5424.)

LioN-X supports the storage of 256 messages in a ring buffer which are sent to the configured Syslog server. When the ring is full with 256 messages, the oldest message is always replaced by the newly arriving messages. All messages can be saved on the Syslog server. The Syslog client of the IO-Link Master will not store any message permanently.

11.5.1 Syslog configuration

In **delivery state**, Syslog functions are **disabled**. The Syslog client can be configured either using the Web interface or directly via a JSON object sent in an HTTP request. For more information see chapter Syslog configuration - Quick start guide on page 179.

The configuration URL is:

```
http://[ip-address]/w/config/syslog.json
```

The configuration can also read back as a JSON file:

```
http://[ip-address]/r/config/syslog.json
```

The configuration is a JSON object. Each JSON member is a configuration element. The object must not contain all elements. Only the provided elements will be changed. The configuration changes apply only after a device restart.

The following configuration elements are available (default values in bold):

Element	Data type	Description	Example data
syslog-enable	boolean	Master switch for the Syslog client	true / false
global-severity	integer	Severity level of Syslog client 0 - Emergency 1 - Alert 2 - Critical 3 - Error 4 - Warning 5 - Notice 6 - Info 7 - Debug The client will log all messages of severity according to the setting, including all below levels.	0/1/2/3/4/5/6/7
server-address	string (IP address)	IP address of the Syslog server	192.168.0.51 (Default: null)
server-port	integer (0 to 65535)	Server port of the Syslog server	514
server-severity	integer (0 to 7)	Severity level of Syslog server 0 - Emergency 1 - Alert 2 - Critical 3 - Error 4 - Warning 5 - Notice 6 - Info 7 - Debug	0/1/2/ 3 /4/5/6/7

Table 63: Syslog configuration

Syslog response:

The resulting response is a JSON object with a "status" field. Status should be "0" if no error occurred, and "-1" if there is an error.

In case of an error, the response contains an error array.

The error array contains an error object for each error occurred. The object consists of a field "Element" which names the config element that caused the error, and of a field "Message" for the error message.

Examples:

```
{"status": -1, "error": [{"Element": "upcua-enable", "Message": "Boolean
expected"}]}

{"status": 0}

{"status": -1, "error": [{"Element": "root", "Message": "Not a JSON
object"}]}
```

11.5.2 Syslog configuration - Quick start guide

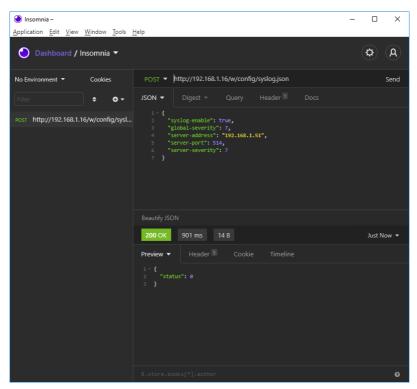


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11.5.2.1 Syslog configuration via JSON

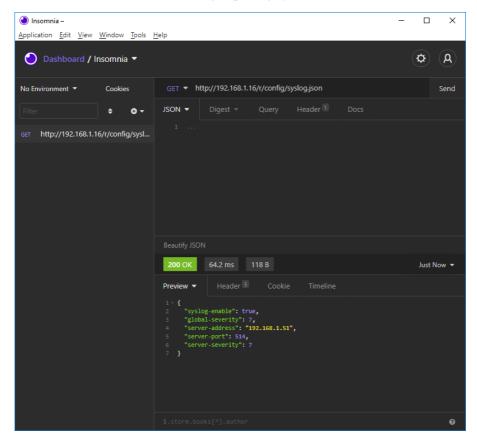
- **1.** Depending on your application case, download and install *Insomnia* or a comparable application: https://insomnia.rest/download/
- 2. Configure Syslog:

POST: [IP-address]/w/config/syslog.json



3. Read Syslog configuration:

GET: [IP-address]/r/config/syslog.json



12 The integrated Web server

LioN-X and the LioN-Xlight variants are equipped with an integrated Web server which makes functions for the device configuration and the display of status and diagnostic information available via a Web interface.

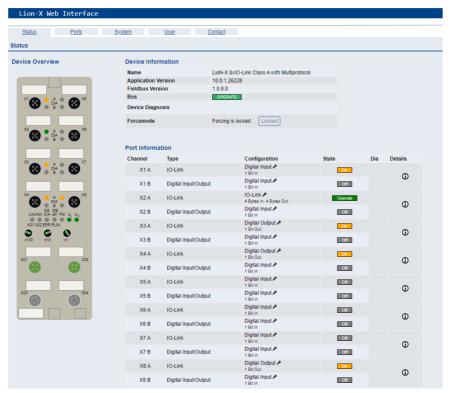
The Web interface provides an overview of the configuration and status of the device. It is also possible to use the Web interface to trigger a reboot, reset to the factory defaults, or perform a firmware update.

Enter http://followed by the IP address, such as http://192.168.1.5, in your Web browser's address bar. If the status page of the device is not displayed, check your browser and firewall settings.

12.1 LioN-X 0980 XSL... variants

12.1.1 The Status page





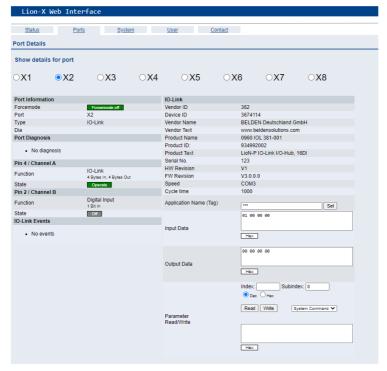
The status page provides a quick overview of the current state of the device.

The left side shows a graphical representation of the module with all its LEDs and the positions of the rotary encoding switches.

The right side shows the "Device Information" table with some basic data for the module; for example, the variant, the cyclic communication status and a diagnostic indicator. The indicator shows whether diagnostics for the module exist. The "Port Information" table shows the configuration and state of the I/O ports.

12.1.2 The Ports page

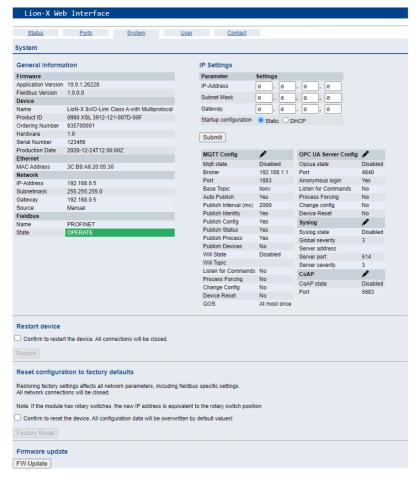




The page shows detailed port information. In the field **Port Diagnosis**, incoming and outgoing diagnostics are displayed as clear text. **Pin 2** and **Pin 4** contain information about the configuration and state of the port. For IO-Link ports, additional information relating to the connected sensor and the process data is displayed.

12.1.3 The System page





The System page shows the basic information for the module like **Firmware** version, **Device** information, **Ethernet**, **Network** and **Fieldbus** information.

Restart Device

The module initializes a software reset.

Reset to Factory Settings

The module restores to the default factory settings.

IP Settings

Use this parameter to change the current IP address of the module.

For PROFINET, this is only useful during commissioning. Normally, the PLC sets the IP address at start-up by detecting the PROFINET module via its device name.

Firmware Update

The module initializes a Firmware update.

For a firmware update choose the *.ZIP container available on our website or ask our support team. Afterwards follow the instructions shown on your screen.



12.1.4 The User page





The User page provides the user management of the Web interface. New users with access rights **Admin** or **Write** can be added here. For security reasons please change the default admin password immediately after configuring the device.

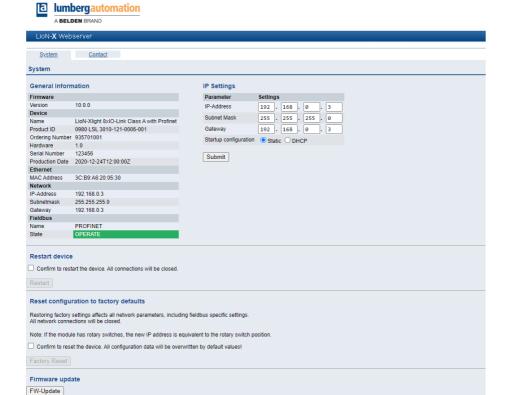
Default user login data:

User: admin

Password: private

12.2 LioN-Xlight 0980 LSL... variants

12.2.1 The System page



The System page shows the basic information for the module like **Firmware** version, **Device** information, **Ethernet**, **Network** and **Fieldbus** information.

Restart Device

The module initializes a software reset.

Reset to Factory Settings

The module restores to the default factory settings.

IP Settings

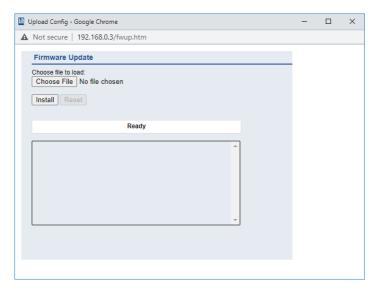
Use this parameter to change the current IP address of the module.

For PROFINET, this is only useful during commissioning. Normally, the PLC sets the IP address at start-up by detecting the PROFINET module via its device name.

Firmware Update

The module initializes a Firmware update.

For a firmware update choose the *.ZIP container available on our website or ask our support team. Afterwards follow the instructions shown on your screen.



13 Technical data

The following sections give an overview of the most important functional data needed to operate the device. For further information and detailed technical data, see the respective **Data Sheet** of your required product in the product specific download area on catalog.belden.com.

13.1 General

Protection class (Only applies if the connectors are screwed together or if protective caps are used.) ⁴	IP65 IP67 IP69K	
Ambient temperature (during operation and storage)	0980 XSL 3x12-121	-40 °C to +70 °C (-40 °F to +158 °F)
	0980 LSL 3x11-121	-20 °C to +60 °C
	0980 LSL 3x10-121	(-4 °F to +140 °F)
Weight	LioN-X 60 mm	ca. 500 gr.
Ambient moisture	Max. 98% RH (For UL applications: Max. 80% RH)	
Housing material	Die-cast zinc	
Surface finish	Frosted nickel	
Flammability class	UL 94 (IEC 61010)	
Vibration resistance (oscillation) DIN EN 60068-2-6 (2008-11)	15 g / 5-500 Hz	
Shock resistance DIN EN 60068-2-27 (2010-02)	50 g / 11 ms +/- X,Y,Z	
Fastening torques	M4 fixing screws	1 Nm
	M4 ground connection	1 Nm
	M12 connector	0.5 Nm
Permitted cables	Ethernet cables according to IEEE 802.3, m Max. length of 100 m, not routed out of facil	,

Table 64: General information

⁴ Not under UL investigation.

13.2 PROFINET protocol

Protocol	PROFINET IO device V2.35
Conformance Class	C (CC-C)
Netload Class	III
Update cycle	1 ms
GSDML file	GSDML-V2.3x-LumbergAutomation-LioN-Xyyyymmdd.xml
Transmission rate	100 Mbit/s, full duplex
Transmission procedure Autonegotiation	100BASE-TX is supported
Vendor ID	16A _H
Device ID	0x0400 (same for all LioN-X variants)
Supported Ethernet protocols	Ping ARP LLDP SNMPv1 (network diagnostics) ▶ Read Community: public ▶ Write Community: private DCP HTTP TCP/IP MRP Client
PROFINET feature	Fast Start-UP Shared Device
Switch functionality	Integrated IRT is supported
PROFINET interface Connections Autocrossing Electrically isolated Ethernet	2 M12 sockets, 4-pin, D-coded (see pin assignments) 2 M12 Hybrid male/female, 8-pin is supported 2000 V DC
Electrically isolated Ethernet ports -> FE	2000 V DC

Table 65: PROFINET protocol

13.3 Power supply of the module electronics/ sensors

Nominal voltage U _S	24 V DC (SELV/PELV)		
Voltage range	18-30 V DC		
Power consumption of module electronics	Typically 160 mA (+/-20 % at U _S nominal voltage)		
Voltage level of the sensor power supply	Min. (U _S – 1.5 V)		
Voltage ripple U _S	Max. 5 %	-	
Power supply interruption	Max. 10 ms	-	
Current consumption sensor system (L+ / Pin 1)	0980 XSL 3912-121	Port X1 – X8 (Pin 1)	max. 4 A per port (at T _{ambient} = 30° C)
(L+7 FIII 1)	0980 LSL 3x11-121	Port X1 – X8 (Pin 1)	max. 2 A per port (at T _{ambient} = 30° C)
	0980 LSL 3x10-121	Port X1 – X4 (L+ / Pin 1)	max. 2 A per port (at T _{ambient} = 30° C)
		Port X5 – X8 (Pin 1)	max. 0.7 A in total for ports X5 – X8
Short circuit/overload protection of sensor supply	Yes, per port		
Reverse polarity protection	Yes		
Operational indicator (U _S)	LED green: 18 V (+/- 1 V) < U _S		
(08)	LED red: U _S < 18 V (+/- 1 V)		
Port X03, X04	M12-L-coded Power, connector/socket, 5-pole Pin 1 / Pin 3		

Table 66: Information on the power supply of the module electronics/ sensors

13.4 Power supply of the actuators

Nominal voltage U _L	24 V DC (SELV/PELV)
Voltage range	18-30 V DC
Voltage ripple U _L	Max. 5 %
Power supply interruption	Max. 10 ms
Reverse polarity protection	Yes
Operational indicator (U _L)	LED green: $18 \text{ V (+/- 1 V)} < U_L$ LED red: $U_L < 18 \text{ V (+/- 1 V)}$ or $U_L > 30 \text{ V (+/- 1 V)}$ * if "Report U_L supply voltage fault" is enabled.
Port X03, X04	M12_L-coded Power, connector/socket, 5-pole Pin 2 / Pin 4

Table 67: Information on the power supply of the actuators

13.5 IO-Link Master ports Class A, Pin 4

0980 XSL 3912-121	Port X1 – X8	M12 socket, 5-pin, Pin 4
0980 LSL 3x11-121		
0980 LSL 3x10-121	Port X1 – X4	

Table 68: IO-Link Master ports, Class A (Ch. A / C/Q / Pin 4)

13.5.1 Configured as a digital input

Input connection	0980 XSL 3912-121	1	Type 1 as per IEC
	0980 LSL 3x11-121		61131-2
	0980 LSL 3x10-121	X1 - X4	Type 1 as per IEC 61131-2
		X5 - X8	Type 1 as per IEC 61131-2
Nominal input voltage	24 V DC		
Input current	Typically 3 mA		
Channel type	Normally open, p-switching		
Number of digital	0980 XSL 3912-121		8
inputs	0980 LSL 3x11-121		
	0980 LSL 3x10-121		
Status indicator	yellow LED		·
Diagnostic indicator	red LED per channel		

Table 69: IO-Link Master Class A ports, pin 4, configured as digital inputs

13.5.2 Configured as a digital output



Attention: For LioN-X variants, the power for the outputs is supplied via the U_L power supply.



Attention: For LioN-Xlight variants, the power for the outputs is supplied via the U_S power supply.

Output type	normally open, p-switching	
Nominal output current per channel Signal status "1" Signal status "0"	min. (U _L -1 V) max. 2 V	
Max. output current per	0980 XSL 3912-121	16 A (M12 Power)
device	0980 LSL 3x11-121	4 A
	0980 LSL 3x10-121	2 A
Max. output current per	0980 XSL 3912-121	2 A
channel ⁵	0980 LSL 3x11-121	0.5 A (power supplied via U _S)
	0980 LSL 3x10-121	0.25 A for UL applications
Short-circuit/overload protected	yes/yes	
Behavior in case of short circuit or overload	disconnection with automatic power-on	1
Number of digital outputs	0980 XSL 3912-121	8
	0980 LSL 3x11-121	
	0980 LSL 3x10-121	4
Status indicator	yellow LED per output	
Diagnostic indicator	red LED per channel	

Table 70: IO-Link Master Ports configured as digital outputs

Max. 2.0 A per channel; max. 6.5 A in total (for **UL applications** max. 5.0 A in total) for every port pair (X1/X2, X3/X4, X5/X6, X7/X8); max. 9.0 A in total (with derating) for the whole port group (X1 .. X8).

13.5.3 Configured as an IO-Link port in COM mode

IO-Link Master specification	v1.1.3 ready, IEC 61131-9
Communication rates	4.8 kbaud (COM 1) 38.4 kbaud (COM 2) 230.4 kbaud (COM 3)
Line lengths in the IO-Link Device	max. 20 m
Number of IO-Link ports	8
Min. IO-Link cycle time	400 µs

Table 71: As an IO-Link port in COM mode

13.6 IO-Link Master ports Class A, Pin 2

0980 XSL 3912-121	Port X1 – X8	M12 socket, 5-pin, Pin 2
0980 LSL 3x11-121		
0980 LSL 3x10-121		

Table 72: IO-Link Master ports, Class A (Ch. B, Pin 2)

13.6.1 Configured as a digital input

Input connection	0980 XSL 3912-121 0980 LSL 3x11-121		Type 1 as per IEC
			61131-2
	0980 LSL 3x10-121	X1 - X4	Type 1 as per IEC 61131-2
		X5 - X8	Type 1 as per IEC 61131-2
Nominal input voltage	24 V DC		
Input current	Typically 3 mA		
Channel type	Normally open, p-switching		
Number of digital	0980 XSL 3912-121		8
inputs	0980 LSL 3x11-121		
	0980 LSL 3x10-121		
Status indicator	white LED		
Diagnostic indicator	red LED per channel		

Table 73: IO-Link Master Class A ports, pin 2, configured as digital inputs

13.6.2 Configured as a digital output



Attention: For LioN-X variants, the power for the outputs is supplied via the U_L power supply.



Attention: For LioN-Xlight variants, the power for the outputs is supplied via the U_S power supply.

Output type	normally open, p-switching	
Nominal output current per channel Signal status "1" Signal status "0"	min. (U _L -1 V) max. 2 V	
Max. output current per device	0980 XSL 3912-121	16 A (M12 Power)
device	0980 LSL 3x11-121	4 A
	0980 LSL 3x10-121	2 A
Max. output current per	0980 XSL 3912-121	2 A
channel ⁶	0980 LSL 3x11-121	0 A (no outputs)
	0980 LSL 3x10-121	
Short-circuit/overload protected	yes/yes	
Behavior in case of short circuit or overload	disconnection with automatic power-on	
Number of digital outputs	0980 XSL 3912-121	8
	0980 LSL 3x11-121	-
	0980 LSL 3x10-121	-
Status indicator	white LED per output	
Diagnostic indicator	red LED per channel	

Table 74: IO-Link Master Ports configured as digital outputs

Max. 2.0 A per channel; max. 6.5 A in total (for **UL applications** max. 5.0 A in total) for every port pair (X1/X2, X3/X4, X5/X6, X7/X8); max. 9.0 A in total (with derating) for the whole port group (X1 .. X8).

13.7 LEDs

U _L	Green	Auxiliary sensor/actuator voltage OK
		18 V (+/- 1 V) < U _L < 30 V (+/- 1 V)
	Red [*]	Auxiliary sensor/actuator voltage LOW
		U_L < 18 V (+/- 1 V) or U_L > 30 V (+/- 1 V)
		* if "Report U $_{L}$ supply voltage fault" is enabled.
	off	None of the above conditions
Us	Green	System/sensor voltage OK
		18 V (+/-1 V) < U _S < 30 V (+/-1 V)
	Red	System/sensor voltage LOW
		$U_{\rm S}$ < 18 V (+/- 1 V) or $U_{\rm S}$ > 30 V (+/- 1 V)
	Flashing red	Device performs a factory reset (position of rotary encoding switches: 9-7-9)
	off	None of the above conditions
X1 X8	Green	IO-Link COM Mode: IO-Link communication exists
A	Flashing green	IO-Link COM Mode: No IO-Link communication.
	Yellow	Standard-IO Mode: Status of digital input or
		output on C/Q (pin 4) line "on"
	off	None of the above conditions
X1 X8	White	Status of digital input or digital output on pin 2 line "on"
В	Red	Short circuit on C/Q (pin 4) line
		/ All modes: Overload or short circuit on L+ (pin 1) line
		/ communication error
	off	None of the above conditions
P1 Lnk/ Act	Green	Ethernet connection to another subscriber exists. Link detected.
P2 Lnk/ Act	Flashing yellow	Data exchange with another subscriber.
	off	No connection to another subscriber. No link, no data exchange.

BF	Red	Bus fault. No configuration, no or slow physical connection
	Red flashing at 2 Hz	Link exists but no communication link to the PROFINET controller
	off	PROFINET controller has established an active connection to the device
DIA	Red	PROFINET module diagnostic alarm active
	Red flashing at 1 Hz	Watchdog time-out; fail safe mode is active
	Red flashing at 2 Hz, 3 sec	DCP signal service is initiated via the bus
	off	None of the above conditions

Table 75: Information on the LED colors

14 Accessories

In order to get access to various types of accessories, please visit our Web page:

http://www.beldensolutions.com